

# A branching and recombination model of technological innovation

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# Outline

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## Scope and motivation

Main focus: the dynamics of technological transitions:

- What endogenous forces drive technological change?
- How technological innovation and technology adoption interact?

More specific questions:

- To what extent **externalities** are important, beyond intrinsic quality, in technology adoption decision?
- What is the role of switching **costs**?
- How important are technological **links**?
- what is the effect of **recombinant** innovation on adoption dynamics?
- How an innovation **policy** can maximize social welfare?

## Positive externalities

For many adoption processes, positive externalities render the utility of an adopter to increase with the number of fellow adopters. Examples:

- technologies,
- social norms,
- scientific ideas

For technology adoption the positive externality is particularly strong because of technological standards.

Positive externalities cause **path-dependence** of technology diffusion. The extreme outcome is technological **lock-in**, where agents are stuck in one technology.

# Literature

- On positive externalities, path-dependence and lock-in: David (1985), Arthur (1989).
- On technological graphs: Vega-Redondo (1994).
- On technology selection: Bruckner et al. (1996).
- On technological modularity and recombinant uncertainty: Fleming (2001), Ethiraj and Levinthal (2004).
- On recombinant innovation: van den Bergh (2008), Zeppini and van den Bergh (2011)

# Main ingredients of the model

An agent-based model, with two entities:

- Technologies
  - have an intrinsic quality
  - exhibit positive externalities
  - form a directed technology graph
- Agents (say entrepreneurs or firms)
  - are homogeneous in their preferences
  - in every period they use one and only one technology
  - they incur switching costs when switching from one to another technology
  - they can invent new technologies

# Agents' utility and technology adoption

The utility from using technology  $\alpha$  in period  $t$  is

$$u_{\alpha,t} = l_{\alpha} + en_{\alpha,t} \quad (1)$$

where  $l_{\alpha}$  is the intrinsic **quality** of technology  $\alpha$ ,  $n_{\alpha,t}$  is the **population** of technology  $\alpha$  in period  $t$  and  $e \in [0, 1]$  is the **strength** of agents' externalities

Agents choose the technology that gives higher utility to them. **Switching** from technology  $\alpha$  to  $\beta$  entails a **cost** equal to the technology **distance**  $d_{\alpha\beta}$ . Then one agent switches if:

$$u_{\beta,t} - d_{\alpha\beta} > u_{\alpha,t} \quad (2)$$

Assumption: adjacent technologies have equal distance  $d_{\alpha\beta} = 1$ .

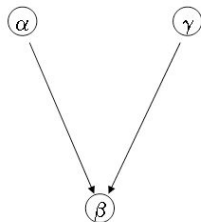
## Two ways to innovations

At each time step  $t$  any agent can be drawn as **innovator** with probability  $p$ , introducing a **new technology** which is an improvement with respect to its previous one. Two cases:

- 1 innovators come from the same technology:  
*branching innovation*
- 2 innovators come from different technologies:  
*recombinant innovation*



Branching event



Recombinant innovation



# Technological progress

Every time step with innovators witnesses a quality improvement.

- In case of branching the improvement is a unitary step up:

$$l_{\beta} = l_{\alpha} + 1 \quad \textit{branching} \quad (3)$$

- When recombinant innovation arises, the quality of the innovation is a unit higher than the maximum quality of parents. If  $\alpha$  and  $\gamma$  recombine to give the innovation  $\beta$ ,

$$l_{\beta} = \max\{l_{\alpha}, l_{\gamma}, \dots\} + 1 \quad \textit{recombination} \quad (4)$$

# Timing of agents' actions

At each time step  $t$ , two stages take place:

- 1 **innovation stage**: a drawn is made and innovator(s) create the new technology
- 2 **decision stage**: remaining agents choose technology by maximizing utility

Assumption: innovators stick to their innovation for one period.

Assumption: in case of tie ( $u_\beta - d_{\alpha\beta} = u_\gamma - d_{\alpha\gamma} = \dots$ ), agents keep their technology if involved, otherwise choose randomly.

Assumption: agents are myopic, not considering their utility contribution. Moreover they are not strategic, missing to anticipate the actions of other agents.

# Successful innovations

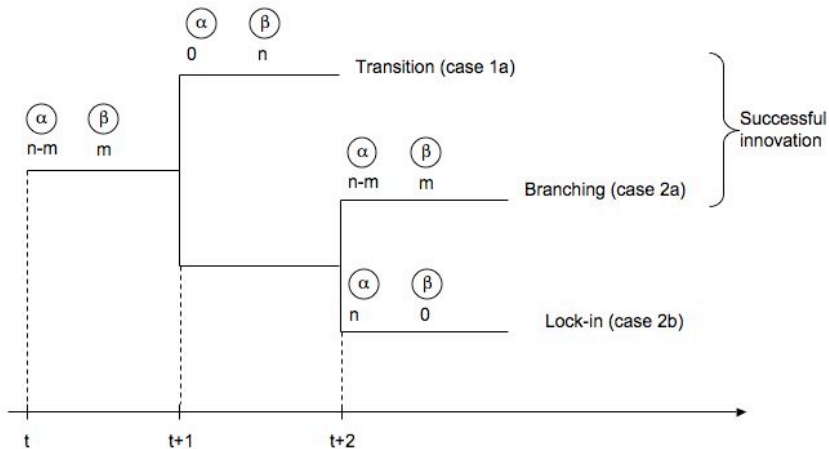
Question: how many agents have to “co-invent” for a *successful innovation* (when non-innovators follow suit)?

Say  $n$  agents use technology  $\alpha$  at time  $t$ , and  $m < n$  agents co-invent technology  $\beta$  in that period. Three cases are possible:

- 1 if  $m > \frac{n}{2}$  we have a *transition* (all agents follow)
- 2 if  $\frac{n}{2} > m > \frac{n}{2} - \frac{1}{e}$  we have a *branching* event ( $n - m$  agents remain with technology  $\alpha$ , the  $m$  innovators remain with  $\beta$ )
- 3 if  $m < \frac{n}{2} - \frac{1}{e}$  we have *lock-in* into technology  $\alpha$  (no escape)



# Technological transitions, branching and lock-in



## Simulation set-up

We first explore qualitatively the effect of the probability of innovation  $p$ , with the following setting:

- 50 agents
- externalities  $e = 0.5$
- time horizon  $T = 50$  steps

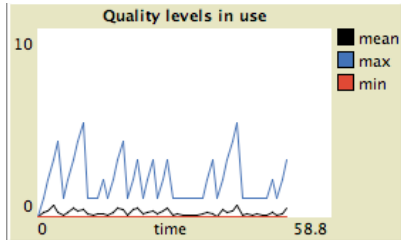
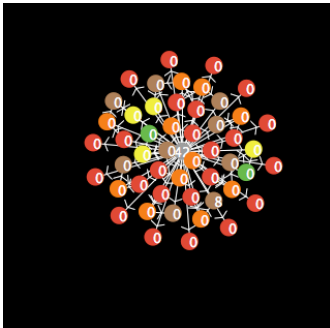
We build up the technology graph and look at the dynamics of quality levels.<sup>1</sup>

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<sup>1</sup>the model has been implemented in Netlogo.

# Lock-in regime

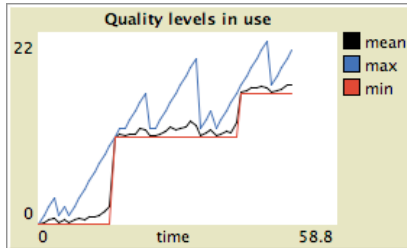
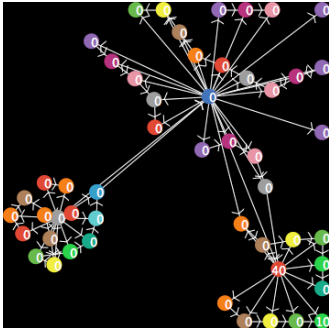
$$p = 0.1$$



**Figure:** Left: technology graph. Right: Minimum quality level of used technologies (red line), maximum level (blue line) and mean level (black line).

# Punctuated growth

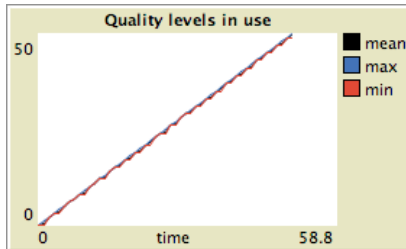
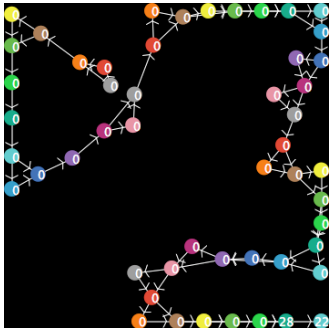
$$p = 0.2$$



**Figure:** Left: technology graph. Right: Minimum quality level of used technologies (red line), maximum level (blue line) and mean level (black line).

# Linear growth

$$p = 0.5$$



**Figure:** Left: technology graph. Right: Minimum quality level of used technologies (red line), maximum level (blue line) and mean level (black line).



## Simulation set-up

With a **simulation experiment** we search quantitatively the parameter space. Here we have set the following conditions:

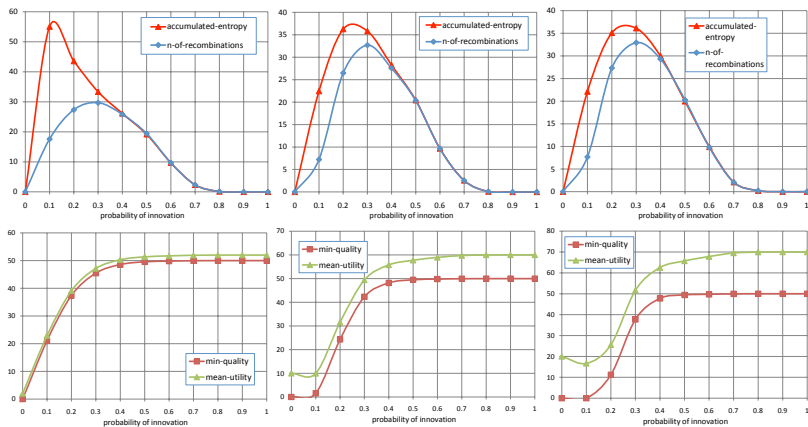
- Agents' **population**  $N = \{2, 5, 10, 20, 50\}$
- **externalities**  $e \in [0, 1]$  with 0.1 steps
- **probability of innovation**  $p \in [0, 1]$  with 0.1 steps

We have chosen a **time horizon** of  $T = 50$  time periods, and for each condition we have **repeated** the simulation 10 times.

Then we average resulting values over these 10 repetitions:

- accumulated quantities (over 50 periods):  
**number of recombinations, entropy**
- final values (after 50 periods):  
technologies' **minimum quality**, agents' **mean utility**

## Results



**Figure:** Simulation with  $N = 20$ . Top: entropy and number of recombinations. Bottom: Minimum quality of used technologies and mean utility across agents. Left:  $e = 0.1$ . Centre:  $e = 0.5$ . Right:  $e = 1$

# Conclusion

Two main messages:

- Technological **recombination** matters: it represents a short-cut to higher quality. Recombinations trigger transitions and consequently boost technological progress.
- There's a **saturation effect** in the innovation probability: above a certain level, the marginal increase in utility is negligible. This means there is an internal optimum for innovation policy effort ( $p$ ). This optimum is highly correlated with the number of technological recombinations.