

Mathematics converts multi-item multiechelon networks into serial multiechelon systems

Ton de Kok

/School of Industrial Engineering

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Real-life supply "chain"





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Definitions

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- h_i added value created (holding cost) at item *i*
- p_k penalty cost per unit short of end-item k
- U_i set of predecessors of *i*, i.e. all child items
- V_i set of successors of *i*, i.e. all child items
- W_i set of all items in the echelon of i
- E_i set of all end-items in the echelon of i
- Y_i echelon inventory position of i
- X_i net stock of item i
- $I_{ki} = \frac{\text{net stock of end-item } k \text{ in a system with root}}{\text{node } i}$

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Base stock policies and linear allocation rules



Key recursion

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$$Z_{j}(t) = q_{j} \left(Z_{i}(t - L_{i}) + D_{i} \left(t - L_{i}, t \right) - \Delta_{j} \right)^{+}$$

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Allocation fractions

• Eppen and Schrage (1981): equal stockout probability

$$q_j = \frac{\sigma_j}{\sum_{m \in V_i} \sigma_m}$$

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• Van der Heijden et al (1997): minimal imbalance

$$q_{j} = \frac{\sigma_{j}^{2}}{2\sum_{j \in V_{i}} \sigma_{m}^{2}} + \frac{\mu_{j}^{2}}{2\sum_{j \in V_{i}} \mu_{m}^{2}}$$

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Optimization problem

- Given allocation fractions, determine base stock levels for all items
- Expressions for costs and performance are similar to expressions for serial systems
- Imbalance should be sufficiently low to ensure validity of analytical results
 - in case imbalance too high, base stock levels should be such that average stocks are increased at upstream stages with high imbalance
 - requires experimental research



Optimal order-up-to-policies for divergent MEIS:

Generalized Newsvendor equations theorem for periodic review systems without setup costs

Optimal order-up-to-policies and allocation functions under balance assumption satisfy generalized Newsvendor equations:

Probability of non-stockout at downstream stockpoint k in the divergent subsystem with stockpoint i as most upstream stage equals

$$P\{I_{ki} \ge 0\} = \frac{p_k + \sum_{j \in U_i} h_j}{p_k + h_k + \sum_{j \in U_k} h_j}$$

or equivalently

$$\left(p_k + \sum_{j \in U_i} h_j\right) = \left(p_k + h_k + \sum_{j \in U_k} h_j\right) P\left\{I_{ki} \ge 0\right\}$$

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Sample path condition on control policies

Assume that each node *i* is controlled according to a policy, which is defined by a parameter ξ_i and possibly other parameters and functions

Sample path condition

If ξ_j is increased by $|E_j|\varepsilon$ for all $j \in W_j$, and there is upstream availability, then a one-time additional flow of ε units is created towards each $k \in E_j$

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Main theorem

• If sample path condition holds then $\forall i \in I$

$$\sum_{k \in E_i} \left(p_k + \sum_{j \in U_k \setminus W_i} h_j \right) = \sum_{k \in E_i} \left(p_k + h_k + \sum_{j \in U_k} h_j \right) P\left\{ I_{ki} \ge 0 \right\}$$

- Proof based on echelon costs and similar to proof of single-item Newsvendor equation
- Relationship can be used as heuristic



Net stocks of end-items

Key recursion

$$Z_{j}(t) = q_{j} \left(Z_{i}(t - L_{i}) + D_{i} \left(t - L_{i}, t \right) - \Delta_{j} \right)^{+}$$

with

$$D_{L_i} = D_i \left(t - L_i, t \right]$$

results into

$$I_{ki} = S_k - \left\{ \left(...q_n \left(q_j \left(D_{L_i} - \Delta_i \right)^+ + D_{L_j} - \Delta_j \right)^+ + ... \right)^+ + D_{L_k + 1} \right\}, k \in E_n, n \in V_j, j \in V_i$$
 and

$$P\left\{I_{ki} \ge 0\right\} = P\left\{\left(\left(\dots q_n \left(q_j \left(D_{L_i} - \Delta_i\right)^+ + D_{L_j} - \Delta_j\right)^+ + \dots\right)^+ + D_{L_k+1} - S_k\right)^+ = 0\right\}, k \in E_n, n \in V_j, j \in V_i$$
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Ruin probabilities and generalized Newsboy equations

Let $X_1, ..., X_N$ be independent random variables and $x_1, ..., x_N$ be nonnegative real numbers. Then

$$P\left\{\left(\left(\left(X_{N}-x_{N}\right)^{+}+X_{N-1}-x_{N-1}\right)^{+}+\ldots\right)^{+}+X_{1}-x_{1}\right)^{+}=0\right\}=P\left\{X_{1}\leq x_{1},X_{1}+X_{2}\leq x_{1}+x_{2},\ldots,\sum_{i=1}^{N}X_{i}\leq \sum_{i=1}^{N}x_{i}\right\}$$

I.e. non-stockout probabilities in multi-echelon order-up-to-systems are equivalent to general finite horizon ruin probabilities



Finite horizon ruin probabilities

• Non-stockout probabilities $P\{I_{ki} \ge 0\}$ can be written as finite horizon ruin probabilities

$$P\{I_{ki} \ge 0\} = P\{\sum_{k=1}^{j} X_{k} \le \xi_{j}, j = 1, ..., i\}$$

Expressions can be accurately approximated recursively

$$G_{i}(\xi_{1},...,\xi_{i}) = P\left\{\sum_{k=1}^{j} X_{k} \leq \xi_{j}, j = 1,...,i\right\}$$

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Recursive computations

• Define random variables *Y_i*

$$\begin{split} &P\left\{Y_{1} \leq x\right\} = P\left\{X_{1} \leq x\right\} \\ &P\left\{Y_{i} \leq x\right\} = \frac{G_{i}(\xi_{1}, \dots, \xi_{i-1}, x)}{G_{i-1}(\xi_{1}, \dots, \xi_{i-1})}, x \geq 0, \ i=2,\dots,N. \end{split}$$

• Theorem

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$$P\{Y_{i} \le x\} = \frac{P\{X_{i} + Y_{i-1} \le x, Y_{i-1} \le \xi_{i-1}\}}{P\{Y_{i-1} \le \xi_{i-1}\}}, i = 2, ..., N$$

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Two-moment recursion

• Fit mixture of Erlang distributions on $E[Y_i]$ and $\sigma^2(Y_i)$

$$E[Y_{i}] = E[X_{i}] + E[Y_{i-1}|Y_{i-1} \le \xi_{i-1}], \ i = 2, ..., N-1$$

$$\sigma^{2}(Y_{i}) = \sigma^{2}(X_{i}) + \sigma^{2}(Y_{i-1}|Y_{i-1} \le \xi_{i-1}), \ i = 2, ..., N-1$$

• Compute $P\{I_{ki} \ge 0\} = G_i(\xi_1, ..., \xi_i)$ recursively $G_1(\xi_1) = P\{Y_1 \le \xi_1\}$ $G_i(\xi_1, ..., \xi_i) = P\{Y_i \le \xi_i\} G_{i-1}(\xi_1, ..., \xi_{i-1}), i = 2, ..., N$



Main theorem

• If sample path condition holds then $\forall i \in I$

$$\sum_{k \in E_i} \left(p_k + \sum_{j \in U_k \setminus W_i} h_j \right) = \sum_{k \in E_i} \left(p_k + h_k + \sum_{j \in U_k} h_j \right) P\left\{ I_{ki} \ge 0 \right\}$$

- Proof based on echelon costs and similar to proof of single-item Newsvendor equation
- Relationship can be used as heuristic



Key transformations for divergent systems

Optimality equation can be rewritten as

$$\begin{split} &\sum_{k \in E_j} \phi_k P\left\{I_{ki} \ge 0\right\} = \pi_j \\ &P\{I_{ki} \ge 0\} = P\left\{q_j D_i + \sum_{s=1}^{K_k - 1} Z_{sk}^{(j)} \le q_j \Delta_j + \sum_{s=1}^{K_k - 1} \tilde{\Delta}_{sk}^{(j)}, \left(\left(\dots (Z_{K_k - 1k}^{(j)} - \tilde{\Delta}_{K_k - 1k}^{(j)})^+ + \dots\right)^+ + Z_{1k}^{(j)} - \tilde{\Delta}_{1k}^{(j)})^+ = 0\right\} \\ &\xi_j = \max_{k \in E_j} \sum_{s=1}^{K_k - 1} \tilde{\Delta}_{sk}^{(j)} \\ &x = q_j \Delta_j + \xi_j \\ &P\{I_{ki} \ge 0\} = P\left\{q_j D_i + \sum_{s=1}^{K_k - 1} Z_{sk}^{(j)} + \xi_j - \sum_{s=1}^{K_k - 1} \tilde{\Delta}_{sk}^{(j)} \le x, \left(\left(\dots (Z_{K_k - 1k}^{(j)} - \tilde{\Delta}_{K_k - 1k}^{(j)})^+ + \dots\right)^+ + Z_{1k}^{(j)} - \tilde{\Delta}_{1k}^{(j)})^+ = 0\right\} \end{split}$$

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Key transformations for divergent systems

$$P\left\{\theta = k\right\} = \phi_k$$

$$\sum \phi_k P\left\{I_{ki} \ge 0\right\} = P\left\{I_{\theta i} \ge 0, \theta \in E_j\right\}$$

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$$k \in E_j$$

Optimality equation can be rewritten as

$$P\left\{q_{j}D_{i} + \sum_{s=1}^{K_{\theta}-1} Z_{s\theta}^{(j)} + \xi_{j} - \sum_{s=1}^{K_{\theta}-1} \tilde{\Delta}_{s\theta}^{(j)} \le x, ((\dots(Z_{K_{\theta}-1\theta}^{(j)} - \tilde{\Delta}_{K_{\theta}-1\theta}^{(j)})^{+} + \dots)^{+} + Z_{1\theta}^{(j)} - \tilde{\Delta}_{1\theta}^{(j)})^{+} = 0, \theta \in E_{j}\right\}$$

$$Y_{j} = \left(\sum_{s=1}^{K_{\theta}-1} Z_{s\theta}^{(j)} - \sum_{s=1}^{K_{\theta}-1} \tilde{\Delta}_{s\theta}^{(j)} + \xi_{j} \left| ((\dots(Z_{K_{\theta}-2\theta}^{(j)} - \tilde{\Delta}_{K_{\theta}-2\theta}^{(j)})^{+} + \dots)^{+} + Z_{1\theta}^{(j)} - \tilde{\Delta}_{1\theta}^{(j)})^{+} = 0, \theta \in E_{j}\right)$$

Optimality equation can be rewritten as

$$P\left\{q_{j}D_{i}+\left(Y_{j}\left|Y_{j}\leq\xi_{j}\right.\right)\leq x\right\}=\frac{\pi_{j}}{\sum_{n\in V_{j}}\pi_{n}}$$

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Key transformations for divergent systems

Considering successor n of j, we find

$$\left(Y_{j} \middle| \theta \in E_{n}\right) = D_{j} + \xi_{j} - \Delta_{n} - \frac{\xi_{n}}{q_{n}} + \frac{1}{q_{n}} \left(Y_{n} \middle| Y_{n} \leq \xi_{n}\right),$$

resulting in the following recursive relationship

$$\mathbf{P}\left\{Y_{j} \leq x\right\} = \sum_{n \in V_{j}} \left(\frac{\sum_{k \in E_{n}} \phi_{k}}{\sum_{k \in E_{j}} \phi_{k}}\right) P\left\{D_{j} + \frac{1}{q_{n}}\left(Y_{n} \left|Y_{n} \leq \xi_{n}\right.\right) \leq x - \xi_{j} + \Delta_{n} + \frac{\xi_{n}}{q_{n}}\right\}$$

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Computational efficiency

- Solving cost-balance equations or generalized Newsvendor equations is equivalent to solving a one-dimensional bisection scheme to find a target value in (0,1)
- Finding base stock levels for N-item divergent structure requires solution of N bisection schemes
 - As efficient as solving N single-echelon systems
- Finding base stock levels for N-item general systems requires solution of at most 3N bisection schemes



Transformation towards review period 1

- With nested review period the system runs through a "super cycle" with length equal to the review period of the root node *R*_N
- For each item we must distinguish R_N / R_i different cycles
- For the simplest (serial) situation we need to consider for item $i R_N / R_i$ different random variables $W_{m_{N,m_{N-1},...,m_i}} = D\left(\sum_{j=i+1}^N (L_j + m_j R_{j-1}), \sum_{j=i}^N (L_j + m_j R_{j-1})\right)$
- Which are aggregated into

$$\hat{W}_{i} = D\left(\sum_{j=i+1}^{N} \left(L_{j} + M_{j}R_{j-1}\right), \sum_{j=i}^{N} \left(L_{j} + M_{j}R_{j-1}\right)\right], P\left\{M_{j} = m\right\} = \frac{R_{j-1}}{R_{j}}$$

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Open issues to be resolved

- Recursive gamma fit approach becomes less accurate as the number of echelons increases
- The aggregation approach for the lot sizing case needs to take into account that as $\frac{R_{j-1}}{R_j}$ approaches infinity

$$\hat{W}_{i} = D\left(\sum_{j=i+1}^{N} (L_{j} + M_{j}R_{j-1}), \sum_{j=i}^{N} (L_{j} + M_{j}R_{j-1})\right)$$

- approaches a uniform distribution, i.e. does not resemble a gamma distribution
- Currently this problem is addressed by not aggregating the random variables involved /School of Industrial Engineering