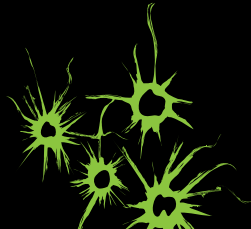


# The $PH/PH/1$ multi-threshold queue

Niek Baer (UT)

joint work with Richard J. Boucherie (UT) and  
Jan-Kees van Ommeren (UT)



# Overview

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Introduction

*PH/PH/1* multi-threshold queue

LDQBD

Generalisations

Conclusion

# Overview

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## Introduction

*PH/PH/1* multi-threshold queue

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# Introduction

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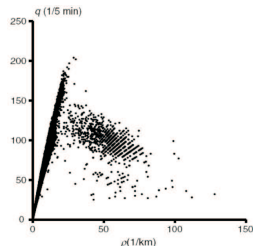
PhD-student since November 2010.

Working on a queueing network able to mimic behaviour of highway traffic.

# Traffic Behaviour

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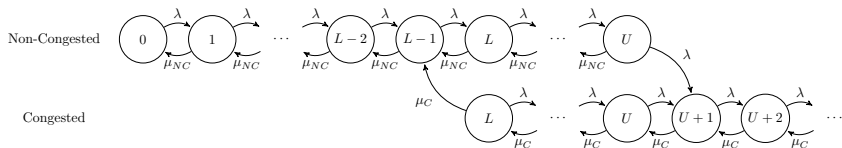
**Capacity Drop** - The transition from non-congested to congested traffic when density reaches an *upper* critical density. The density needs to decrease to a *lower* critical density to resolve congestion.



**Shockwaves** - The propagation of the capacity drop along traffic.

## $M/M/1$ threshold queue

**Capacity Drop** - The transition from non-congested to congested traffic when density reaches a critical density. The density needs to decrease to a lower critical density to resolve congestion.



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## Model Description

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- ▶  $PH/PH/1$  queue with **stage**-dependent service and arrival processes.
- ▶ In stage  $s$ ,  $PH(\mathbf{\Lambda}_s, \lambda_s)$  and  $PH(\mathbf{M}_s, \mu_s)$ .



## Model Description

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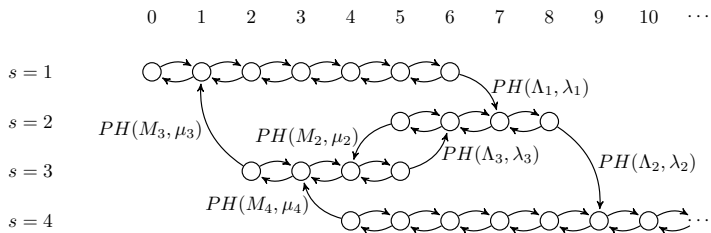
- ▶ *PH/PH/1* queue with **stage**-dependent service and arrival processes.
- ▶ In stage  $s$ ,  $PH(\mathbf{\Lambda}_s, \lambda_s)$  and  $PH(\mathbf{M}_s, \mu_s)$ .
- ▶  $S$ -stages controlled by a threshold policy.
- ▶ Each stage  $s$  has a *lower* threshold  $L_s$  and an *upper* threshold  $U_s$ , but  $L_0 = 0$  and  $U_S = \infty$ .

## Model Description

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- ▶  $PH/PH/1$  queue with **stage**-dependent service and arrival processes.
- ▶ In stage  $s$ ,  $PH(\mathbf{\Lambda}_s, \lambda_s)$  and  $PH(\mathbf{M}_s, \mu_s)$ .
- ▶  $S$ -stages controlled by a threshold policy.
- ▶ Each stage  $s$  has a *lower* threshold  $L_s$  and an *upper* threshold  $U_s$ , but  $L_0 = 0$  and  $U_S = \infty$ .
- ▶ Arrival in  $U_s : (U_s, s) \rightarrow (U_{s+1}, u_s)$ .  
Departure in  $L_s : (L_s, s) \rightarrow (L_{s-1}, l_s)$ .

# Model Description



	$L_s$	$l_s$	$u_s$	$U_s$
$s = 1$	0	—	2	6
$s = 2$	5	3	4	8
$s = 3$	2	1	2	5
$s = 4$	4	3	—	$\infty$

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# Level Dependent Quasi-Birth-and-Death process.

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We model this queue as a Level Dependent Quasi-Birth-and-Death process.

Level: Number of customers.

Phase: Combination of **stage** and **state** of the *PH*-distributions.

# Generator

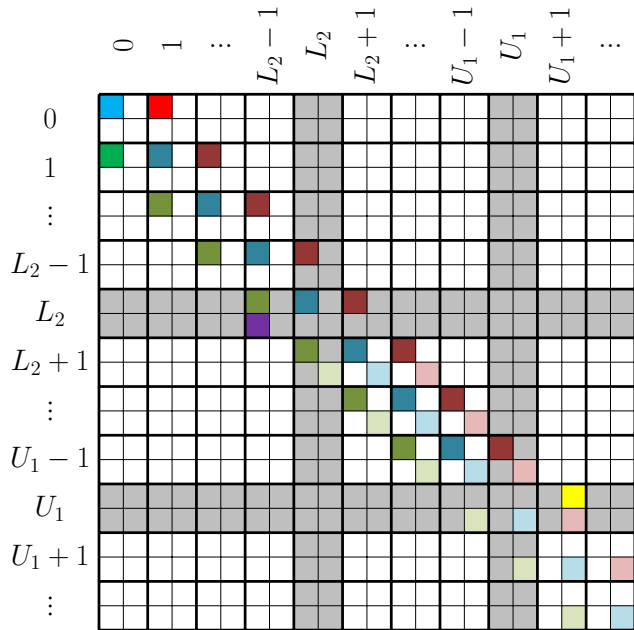
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$$\mathbf{Q} = \begin{bmatrix}
 \mathbf{L}^{(0)} & \mathbf{F}^{(0)} & 0 & \dots & & & \\
 \mathbf{B}^{(1)} & \mathbf{L}^{(1)} & \mathbf{F}^{(1)} & \ddots & & & \\
 0 & \mathbf{B}^{(2)} & \mathbf{L}^{(2)} & \ddots & & & \\
 \vdots & \ddots & \ddots & \ddots & \mathbf{F}^{(i-1)} & & \\
 & & & & \mathbf{B}^{(i)} & \mathbf{L}^{(i)} & \ddots \\
 & & & & & \ddots & \ddots
 \end{bmatrix}.$$

$$F_{(s,j)}^{(i)} = \begin{cases} \Lambda_s^0 \otimes \lambda_s \otimes I_{q_s} & \text{if } j = s \text{ and } L_s \leq i < U_s, \\ \Lambda_s^0 \otimes \mathbf{e}_{q_s} \otimes \lambda_{u_s} \otimes \mu_{u_s} & \text{if } j = u_s \text{ and } i = U_s, \\ 0 & \text{otherwise.} \end{cases}$$

$$L_{(s,j)}^{(i)} = \begin{cases} \Lambda_s \otimes I_{q_s} + I_{p_s} \otimes M_s & \text{if } j = s, i > 0 \text{ and } L_s \leq i \leq U_s, \\ \Lambda_s \otimes I_{q_s} & \text{if } j = s = 1 \text{ and } i = 0, \\ 0 & \text{otherwise.} \end{cases}$$

$$B_{(s,j)}^{(i)} = \begin{cases} I_{p_s} \otimes M_s^0 \otimes \mu_s & \text{if } j = s \text{ and } L_s < i \leq U_s, \\ \mathbf{e}_{p_s} \otimes M_s^0 \otimes \lambda_{l_s} \otimes \mu_{l_s} & \text{if } j = l_s \text{ and } i = L_s, \\ 0 & \text{otherwise.} \end{cases}$$





## Stationary Queue Length probabilities

---

$$\pi_i = \pi_0 \prod_{n=0}^{i-1} \mathbf{R}^{(n)}$$

$$\pi_0 \left( \mathbf{L}^{(0)} + \mathbf{R}^{(0)} \mathbf{B}^{(1)} \right) = \mathbf{0}$$

$$\pi_0 \left( \sum_{i=0}^{\infty} \prod_{n=0}^{i-1} \mathbf{R}^{(n)} \right) \mathbf{e} = \mathbf{1}$$

with  $\mathbf{R}^{(i)}$  the minimal nonnegative solution to

$$\mathbf{F}^{(i)} + \mathbf{R}^{(i)} \mathbf{L}^{(i+1)} + \mathbf{R}^{(i)} \mathbf{R}^{(i+1)} \mathbf{B}^{(i+2)} = \mathbf{0}, \quad i \geq 0$$

## Stationary Queue Length probabilities

---

$$\mathbf{0} = \mathbf{F}^{(i)} + \mathbf{R}^{(i)} \mathbf{L}^{(i+1)} + \mathbf{R}^{(i)} + \mathbf{R}^{(i+1)} \mathbf{B}^{(i+2)}, \quad i \geq 0$$
$$\mathbf{R}^{(i)} = -\mathbf{F}^{(i)} \left( \mathbf{L}^{(i+1)} + \mathbf{R}^{(i+1)} \mathbf{B}^{(i+2)} \right)^{-1}$$

- ▶ Find  $R^{(K)}$ ,  $K$  large enough.
- ▶ Does the inverse exist?

- ▶ System is level independent above level

$$\max_{s, U_s < \infty} \{U_s\} + 1.$$

$\mathbf{R}^{(K)}$  is the minimal nonnegative solution to

$$\mathbf{F} + \mathbf{R}\mathbf{L} + \mathbf{R}^2\mathbf{B} = \mathbf{0}$$

- ▶ Suppose  $S = 3$ , then in the tail:

$$\mathbf{L} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & L \end{bmatrix} \quad \mathbf{B} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & B \end{bmatrix} \quad \mathbf{R} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & R \end{bmatrix}$$

and  $[\mathbf{L} + \mathbf{R}\mathbf{B}]^{-1}$  does not exist.

## Decomposition Method

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Solve

$$\mathbf{F}^{(i)} + \mathbf{R}^{(i)} \mathbf{L}^{(i+1)} + \mathbf{R}^{(i)} \mathbf{R}^{(i+1)} \mathbf{B}^{(i+2)} = \mathbf{0}, \quad i \geq 0$$

or for  $j, k = 1, \dots, S$

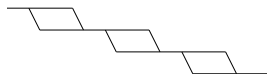
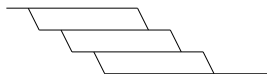
$$\mathbf{F}_{(j,k)}^{(i)} + \sum_{a=1}^S \mathbf{R}_{(j,a)}^{(i)} \mathbf{L}_{(a,k)}^{(i+1)} + \sum_{a=1}^S \sum_{b=1}^S \mathbf{R}_{(j,a)}^{(i)} \mathbf{R}_{(a,b)}^{(i+1)} \mathbf{B}_{(b,k)}^{(i+2)} = \mathbf{0}, \quad i \geq 0$$

Most cases result in solving these linear equations.

## Explicit Results

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**If:**  $F^{(i)}$  is upper triangular,  $B^{(i)}$  is lower triangular and  $B_{(j,k)}^{(i)} = \mathbf{0}$  for  $j - k > 1$ , **then**  $R^{(i)}$  is upper triangular



## Explicit Results

---

If:  $\mathbf{F}^{(i)}$  is upper triangular,  $\mathbf{B}^{(i)}$  is lower triangular and  $\mathbf{B}_{(j,k)}^{(i)} = \mathbf{0}$  for  $j - k > 1$ , then  $\mathbf{R}^{(i)}$  is upper triangular and

$$\mathbf{F}_{(j,k)}^{(i)} + \sum_{a=1}^S \mathbf{R}_{(j,a)}^{(i)} \mathbf{L}_{(a,k)}^{(i+1)} + \sum_{a=1}^S \sum_{b=1}^S \mathbf{R}_{(j,a)}^{(i)} \mathbf{R}_{(a,b)}^{(i+1)} \mathbf{B}_{(b,k)}^{(i+2)} = \mathbf{0}, \quad i \geq 0$$

can be simplified to find

$$\begin{aligned} \mathbf{R}_{(j,j)}^{(i)} &= f(\mathbf{R}^{(i+1)}) \\ \mathbf{R}_{(j,k)}^{(i)} &= g(\mathbf{R}^{(i+1)}, \mathbf{R}_{(j,j)}^{(i)}, \dots, \mathbf{R}_{(j,k-1)}^{(i)}) \end{aligned}$$

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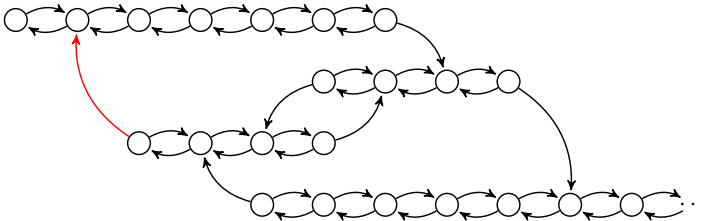
# Generalisations

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- ▶ Multiple zeros
- ▶ Multiple tails
- ▶ Stochastic stage changes

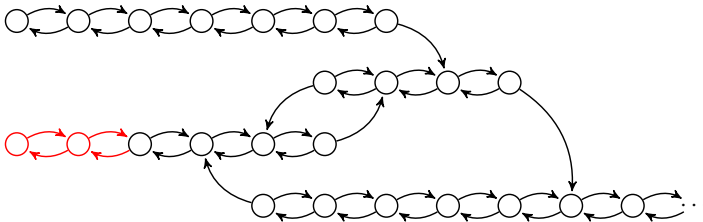


# Multiple zeros



	$L_s$	$I_s$	$u_s$	$U_s$
$s = 1$	0	—	2	6
$s = 2$	5	3	4	8
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$s = 4$	4	3	—	$\infty$

# Multiple zeros



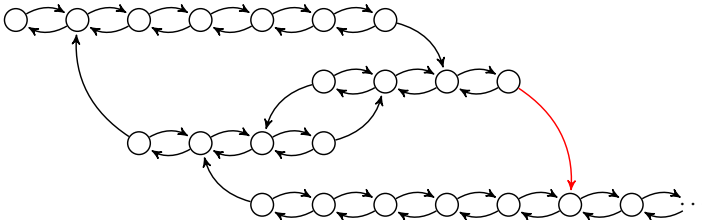
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$$F_{(s,j)}^{(i)} = \begin{cases} \Lambda_s^0 \otimes \lambda_s \otimes I_{q_s} & \text{if } j = s \text{ and } L_s \leq i < U_s, \\ \Lambda_s^0 \otimes \mathbf{e}_{q_s} \otimes \lambda_{u_s} \otimes \mu_{u_s} & \text{if } j = u_s \text{ and } i = U_s, \\ 0 & \text{otherwise.} \end{cases}$$

$$L_{(s,j)}^{(i)} = \begin{cases} \Lambda_s \otimes I_{q_s} + I_{p_s} \otimes M_s & \text{if } j = s, i > 0 \text{ and } L_s \leq i \leq U_s, \\ \Lambda_s \otimes I_{q_s} & \text{if } j = s = 1, 3 \text{ and } i = 0, \\ 0 & \text{otherwise.} \end{cases}$$

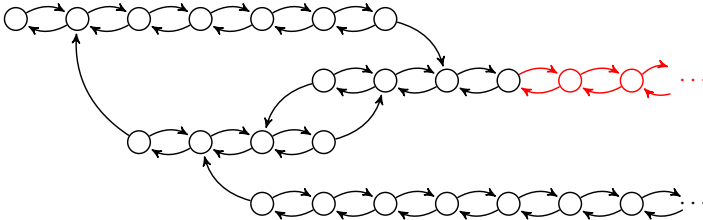
$$B_{(s,j)}^{(i)} = \begin{cases} I_{p_s} \otimes M_s^0 \otimes \mu_s & \text{if } j = s \text{ and } L_s < i \leq U_s, \\ \mathbf{e}_{p_s} \otimes M_s^0 \otimes \lambda_{l_s} \otimes \mu_{l_s} & \text{if } j = l_s \text{ and } i = L_s, \\ 0 & \text{otherwise.} \end{cases}$$

# Multiple tails



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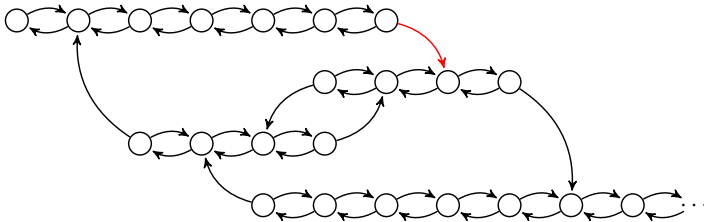
## Multiple tails



	$L_s$	$I_s$	$u_s$	$U_s$
$s = 1$	0	—	2	6
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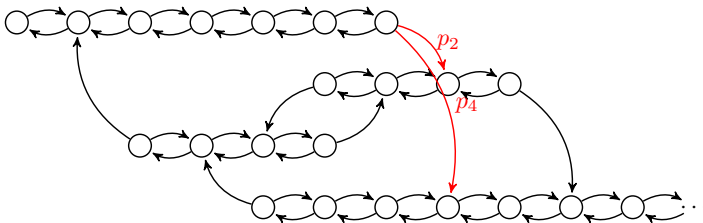
# Stochastic stage changes

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# Stochastic stage changes

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$$\mathbf{F}_{(s,j)}^{(i)} = \begin{cases} \mathbf{\Lambda}_s^0 \otimes \lambda_s \otimes \mathbf{I}_{q_s} & \text{if } j = s \text{ and } L_s \leq i < U_s, \\ \mathbf{p}_{u_s} \cdot \mathbf{\Lambda}_s^0 \otimes \mathbf{e}_{q_s} \otimes \lambda_{u_s} \otimes \mu_{u_s} & \text{if } j = u_s \text{ and } i = U_s, \\ 0 & \text{otherwise.} \end{cases}$$

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# Conclusions and Further Research

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For now:

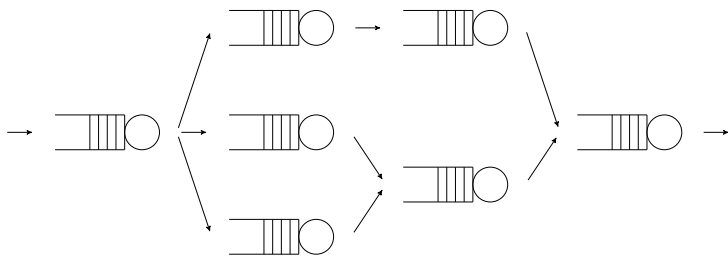
- ▶ Decomposition Method for the  $PH/PH/1$  multi-threshold queue.

The next steps:

- ▶ Analyse (tandem) networks of  $PH/PH/1$  threshold queues.
- ▶ Analyse (tandem) networks of  $PH/PH/1$  **feedback** threshold queues.

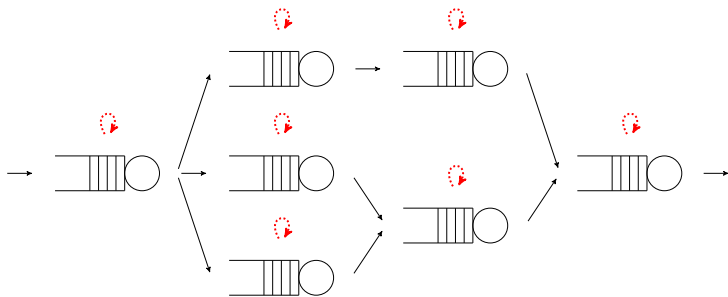
# Networks

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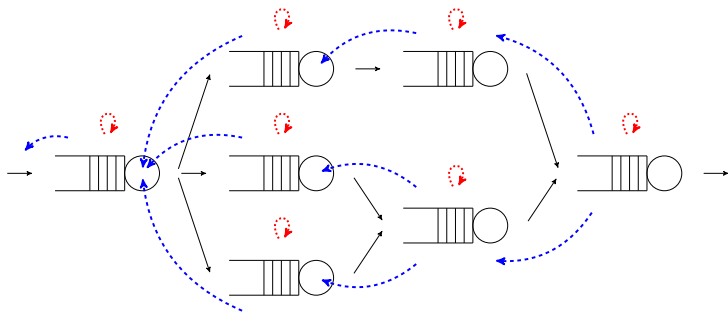
# Networks with thresholds

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# Networks with feedback thresholds

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# Questions?

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