Biological context		A PDE approach	Third approach	

Adaptive dynamics in the limit of small populations in a stochastic individual-based model

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Workshop "Population Dynamics and Statistical Physics in Sinergy", Eurandom, Eindhoven, August 28, 2014

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Biological context ●○○		A PDE approach	Third approach 0000000000000	
Adaptive dynamics				

Adaptive dynamics

Darwinian evolution: Three main ingredients

- Heredity: transmissions of individual characteristics from a generation to the next one.
- Mutation: cause of the variability in individual characteristics.
- Selection: consequence of the interactions between individuals and their environment, including the rest of the population (ecology).

Adaptive dynamics (since the 90s): Hofbauer and Sigmund (1990), Metz, Geritz et al. (1992,1996), Dieckmann and Law (1996)...

- Focus on the interplay between ecology and evolution
- Ecological interactions modeled in detail
- Heredity is simplified as much as possible: asexual (clonal) reproduction



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Adaptive dynamics				

Adaptive dynamics

 \rightsquigarrow Density-dependent individual-based models where no fitness is given. The fitness landscape has to be constructed from the parameters of the model.

→ New phenomenon of evolutionary branching (Metz et al., 1996)

- Transition from a population concentrated around a single phenotype to a population concentrated around several distinct phenotypes, still under ecological interaction
- Mechanism of diversification
- Can lead to speciation without geographical separation (Dieckmann and Doebeli, 1999)
- \leadsto Three biological assumptions (Metz et al., 1996):
 - large populations
 - rare mutations
 - small mutation steps



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Adaptive dynamics				

Evolutionary banching





Biological context	The model ●0000	A PDE approach	Third approach	
The model				

Individual-based model

Birth-death-competition-mutation process (Metz et al. 1996, Bolker-Pacala 97, Kisdi 99, Dieckmann-Law 00, Doebeli-Dieckmann 01, Fournier-Méléard 04, C.-Ferrière-Méléard 06...).

- Each individual characterized by a continuous phenotypic trait x ∈ X ⊂ ℝ (individual size, age at maturity, rate of food intake...).
- K scales the size of the population
- μ scales the probability of mutation
- σ scales the size of mutation steps
- At time t, the population is composed of $N_K(t)$ individuals with weights $\frac{1}{K}$ and traits $x_1, \ldots, x_{N_K(t)} \in \mathcal{X}$:

$$\nu_t^K = \frac{1}{K} \sum_{i=1}^{N_K(t)} \delta_{x_i}.$$

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The model				

Transition rates for an individual with trait x

- Reproduction at rate b(x):
 - With probability 1μ , clonal reproduction (offspring with trait x).
 - With probability μ , mutation, and the mutant trait is $x + \sigma H$, where $H \sim m(h)dh$, symmetric w.r.t. 0 (e.g. Gaussian distribution).
- Death without competition at rate d(x).
- Death from competition with any other individual of trait y at rate $\frac{1}{K}c(x, y)$.

 \leadsto an individual with trait x dies at density dependent rate

$$\begin{aligned} d(x) &+ \frac{1}{K} \sum_{i=1}^{N_K(t)} c(x, x_i) - c(x, x) \\ &= d(x) + \int_{\mathcal{X}} c(x, y) \left(\nu_t^K(dy) - \frac{1}{K} \delta_x(dy) \right). \end{aligned}$$

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The model				

On the limit $K \to +\infty$

Assume $b(x) \equiv b$, $d(x) \equiv d$ and $c(x, y) \equiv c$ (neutral case).

Then the total number of individuals N_t^K is a Markov birth and death process with

- birth rate **bn**
- death rate $\frac{dn + cn \frac{n-1}{K}}{K}$ when $N_t^K = n$.

It is well known that N_t^K/K converges when $K\to+\infty$ to the solution of the logistic equation

$$\dot{n} = n(b - d - cn).$$

Remark: also true if $\nu_0^K \to n_0 \delta_x$ and $\mu = 0$, with b = b(x), d = d(x) and c = c(x, y) (monomorphic case). We will use the notation

$$\bar{n}(x) = \frac{b(x) - d(x)}{c(x, x)}$$

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the equilibrium of the logistic equation (monomorphic equilibrium).

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Example				
Example				

Roughgarden (1976,1979), Dieckmann-Doebeli (1999)

- $\mathcal{X} = [-2, 2]$ $d(x) \equiv 0$ $u_K = 1$ p(x) = p.
- $m(h)dh = \mathcal{N}(0, 1)$ (conditioned on $x + h \in \mathcal{X}$).
- $b(x) = \exp\left(-\frac{x^2}{2\sigma_b^2}\right)$, maximum at 0.
- Symmetric competition for resources:

$$\alpha(x, y) = \alpha(x - y) = \exp\left(-\frac{(x - y)^2}{2\sigma_{\alpha}^2}\right).$$



Biological context	The model ○○○○●	A PDE approach	Third approach	
Example				

Simulations



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$$\mu = 0.1, K = 1000, \sigma = 0.01,$$

 $\sigma_b = 0.9, \sigma_\alpha = 0.7.$

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Rare mutations				

Simulations: rare mutations



 $\mu = 0.0001, K = 1000,$ $\sigma = 0.08, \sigma_b = 0.9, \sigma_{\alpha} = 1.0.$ $\sigma = 0.08, \sigma_b = 0.9, \sigma_{\alpha} = 0.7.$

 $\mu = 0.0001, K = 1000,$

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Lotka-Volterra systems				

Limit of rare mutations: Metz et al. 1996

- The selection process has sufficient time between two mutations to eliminate disadvantaged traits.
- Large population assumption: (nearly) deterministic population dynamics between mutations, so that one can predict the outcome of competition between the traits.

 \rightsquigarrow Succession of phases of (random) mutant invasion, and phases of (fast, deterministic) competition between traits.

Adaptive walk in a fitness landscape that depends on the current state of the population: fitness of a mutant trait y in a population x at equilibrium

$$f(y,x) = b(y) - d(y) - c(y,x)\overline{n}(x)$$

(C., 2006, C. and Méléard 2011, Baar, Bovier, C. \rightarrow next talk !)



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Lotka-Volterra systems				





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Lotka-Volterra systems				





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Lotka-Volterra systems				



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Lotka-Volterra systems				





Canonical Equation of Adaptive Dynamics (first form)

Adaptive walk with small mutations:

When $\mu \to 0, K \to +\infty$ and $\sigma \to 0$ conveniently (Baar, Bovier, C.), on the time scale $\frac{t}{K\mu\sigma^2}$, the individual-based model converges to $(\bar{n}(x(t))\delta_{x(t)}, t \ge 0)$, where x is solution of the ODE

$$rac{dx}{dt} = \int h^2 m(h) dh \, ar{n}(x) \partial_1 f(x;x).$$

- "hill-climbing" process in the fitness landscape (Dieckmann and Law, 1996).
- evolutionary branching can also be described with this approach (C., Méléard, 2011)

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• A criticism (Waxman, Gavrilets, 2005): this approach with rare mutations leads to evolution on a too long time-scale (mutations are too rare).

Biological context		A PDE approach	Third approach	
Hamilton-Jacobi equation w	vith constraints			

Large population limit

Fournier and Méléard, 2004: assuming that ν_0^K converges in law to the measure $u_0(x) dx$ for the weak topology when $K \to +\infty$, then $(\nu_t^K, t \ge 0)$ converges in law to $(u(t, x) dx, t \ge 0)$, where u(t, x) is solution to the PDE

$$\begin{split} \partial_t u(t,x) &= u(t,x) \left((1-\mu)b(x) - d(x) - \int_{\mathcal{X}} c(x,y)u(t,y) \, dy \right) \\ &+ \int_{\mathcal{X}} b(y)\mu u(t,y)m(\frac{x-y}{\sigma}) \, \frac{dy}{\sigma}. \end{split}$$

Assuming $\mu = 1$ and $\sigma = \varepsilon$, this PDE can be written as

$$\begin{split} \partial_t u(t,x) &= \quad u(t,x) \left(r(x) - \int_{\mathbb{R}^\ell} c(x,y) u(t,y) \, dy \right) \\ &+ \quad \int_{\mathbb{R}^\ell} m(h) (u(t,x+\varepsilon h) - u(t,x)) \, dh, \end{split}$$

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Biological context		A PDE approach	Third approach	
Hamilton-Jacobi equation w	vith constraints			

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Assuming $\mu = 1$ and $\sigma = \varepsilon$, this PDE can be written as

$$\begin{split} \partial_t u(t,x) &= \frac{1}{\varepsilon} u(t,x) \left(r(x) - \int_{\mathbb{R}^\ell} c(x,y) u(t,y) \, dy \right) \\ &\quad + \frac{1}{\varepsilon} \int_{\mathbb{R}^\ell} m(h) (u(t,x+\varepsilon h) - u(t,x)) \, dh, \end{split}$$

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scaling time as t/ε (large time, small mutations)

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Hamilton-Jacobi equation v	vith constraints			

Simulation



Competition for two resources (Diekmann, Jabin, Mischler, Perthame, 2005)



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Hamilton-Jacobi equation w	vith constraints			

Limit Hamilton-Jacobi equation (1)

Diekmann et al., 2005: defining (WKB ansatz)

$$u_{\varepsilon}(t,x) = \exp\left(rac{\varphi_{\varepsilon}(t,x)}{\varepsilon}
ight),$$

the PDE becomes

$$\begin{split} \partial_t \varphi_{\varepsilon}(t,x) &= r(x) - \int_{\mathbb{R}^\ell} c(x,y) u_{\varepsilon}(t,y) \, dy \\ &+ \int_{\mathbb{R}^\ell} m(h) \left[\exp\left(\frac{\varphi_{\varepsilon}(t,x+\varepsilon h) - \varphi_{\varepsilon}(t,x)}{\varepsilon}\right) - 1 \right] \, dh. \end{split}$$

This suggests the convergence of φ_{ε} to the solution of

$$\partial_t \varphi(t,x) = r(x) - \int_{\mathbb{R}^\ell} c(x,y) \mu_t(dy) + \beta H(\nabla_x \varphi(t,x)),$$

where

$$H(p) = \int_{\mathbb{R}^{\ell}} \overline{m}(h)(e^{p \cdot h} - 1) \, dh$$

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and μ_t is (in some sense) the limit of $u_{\varepsilon}(t, \cdot)$.

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 Hamilton-Jacobi equation with constraints

Limit Hamilton-Jacobi equation (2)

- The total population mass remains bounded $\rightsquigarrow \max_x \varphi(t, x) = 0$ for all $t \ge 0$.
- The limit population density at time t is 0 except at the points x where $\varphi(t, x) = 0 \quad \rightsquigarrow \quad \mu_t$ has support in $\{\varphi(t, \cdot) = 0\}$.
- The measure μ_t has to be metastable, i.e.

•
$$r(x) - \int c(x, y)\mu_t(dy) \leq 0$$
 for all x such that $\varphi(t, x) = 0$,

• $r(x) - \int c(x, y) \mu_t(dy) = 0$ for all x in the support of μ_t .

• Under the assumption that the kernel c(x, y) is positive, these two conditions are satisfied for a unique measure μ_t , and

 $\mu_t = \mu(\{\varphi(t, \cdot) = 0\}),$

for some well-defined function μ

 \rightsquigarrow closed Hamilton-Jacobi equation (C., Jabin, 2011).

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Hamilton-Jacobi equation v	vith constraints			

Some elements of the proof of the theorem

- The existence and uniqueness of a measure μ_t as above is proved using Lyapunov functions for the PDE without mutations.
- One cannot have existence of a solution to HJ in the strong sense. The support of μ_t need not be continuous.



- We use classical a priori estimates for HJ equations, and prove that they hold for φ_{ε} uniformly in ε . In particular, we prove that $\partial_x \varphi^{\varepsilon}$ is bounded in $L^{\infty}([0, T], BV_{\text{loc}}(\mathbb{R}))$ and $\partial_{xx} \varphi_{\varepsilon} \geq -C$.
- This implies easily the strong convergence of a subsequence of φ_{ε} .
- The difficult part is the convergence of $\int c(x, y)u_{\varepsilon}(t, y)dy$ to the correct limit. This is done by proving uniform Lebesgue-right-continuity estimates.

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Hamilton-Jacobi equation with constraints

Simulation of the PDE for population densities



(Implicit finite differences)



Biological context

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Hamilton-Jacobi equation with constraints

Simulation of the HJ equation with constraints





The canonical equation of adaptive dynamics: second form

- As long as there is only a single point $\bar{x}(t)$ in $\{\varphi(t, \cdot) = 0\}$, $\mu_t = \bar{n}(\bar{x}(t))\delta_{\bar{x}(t)}$.
- Since $\partial_x \varphi(t, \bar{x}(t)) = 0$, we have

$$\partial_{tx}\varphi(t,\bar{x}(t)) + \partial_{xx}\varphi(t,\bar{x}(t))\frac{d\bar{x}(t)}{dt} = 0.$$

• Since
$$\partial_t \varphi(t, x) = f(x, \bar{x}(t)) + H(\partial_x \varphi(t, x)),$$

 $\partial_{tx}\varphi(t,\bar{x}(t)) = \partial_{x}f(x,\bar{x}(t)) + H'(\partial_{x}\varphi(t,\bar{x}(t)))\partial_{xx}\varphi(t,\bar{x}(t)) = \partial_{x}f(x,\bar{x}(t))$

Therefore

$$\frac{d\bar{x}(t)}{dt} = -(\partial_{xx}\varphi(t,\bar{x}(t)))^{-1}\partial_{x}f(x,\bar{x}(t)).$$

 \leadsto same fitness gradient as for the first form, but different speed.



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Biological context		A stochastic approach	A PDE approach	Third approach	
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The canonical equation of a	adantive dynamics: se	cond form			

Mathematical and biological comments

- Open problem: well-posedness of the Hamilton-Jacobi equation with contraint. Only known in special cases (a single resource or no mutation).
- Smoothness of the solution is only known in special cases
 → justification of the canonical equation and of the branching criterion (same criterion as for the first approach) only in special cases.

Biological criticism:

- the dynamics of the population is strongly influenced by very low population densities (so low that there should actually be nobody there)
- evolutionary branching is too fast (also due to very low population densities
- \rightsquigarrow PDE analysts try to modify the model with thresholds or stronger interactions to actually obtain zero densities (see recent works of Jabin, Perthame, Mirrahimi, Lorz).

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Biological context		A PDE approach	Third approach ●OOOOOOOOOOO	
Main result				

Third approach: small mutations and not too large population

This suggests another stochastic approach (already proposed by Meszena, Gyllenberg, Jacobs, Metz, PRL 2005), intermediate between the first two:

- consider the individual-based models with frequent mutations $(\mu = 1)$.
- assume that K is large and σ is small enough for the diameter of the support of the population to be small (concentration limit, as the first too approaches).

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• look at the long term evolution of the population.

Biological context		A PDE approach	Third approach O●OOOOOOOOOO	
Main result				

Canonical equation of adaptive dynamics: third form

Assume for simplicity that $d(x) \equiv 0$ (no extinction).

Theorem

Assume that $b(\cdot)$ and $c(\cdot, \cdot)$ are C^1 , positive functions and $m(\cdot)$ has compact support. Assume that ν_0^K has support $\{x_0\}$ for all K. Assume that $\mu = 1$, $\sigma \to 0$ and $K \to +\infty$ so that

$$\sigma = o(K^{-5/2-a})$$

for some a > 0. Then

$$(\nu_{t/(\sigma^2 K)}^K, t \ge 0) \Rightarrow (\bar{n}(x(t))\delta_{x(t)}, t \ge 0)$$

in law for the Skorohod topology on the space of finite positive measures on \mathcal{X} equipped with the weak topology, where $x(0) = x_0$ and

$$\dot{x}(t) = 2 \operatorname{Var}(m) \overline{n}(x(t)) \partial_1 f(x(t), x(t)).$$

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Biological context		A PDE approach	Third approach ○O●○○○○○○○○○	
Main result				

A few comments

- Same form with fitness gradient.
- Very similar to the first form:
 - in the case of symmetric mutations, only a multiplicative contant;
 - in the case of asymmetric mutations, no longer the same.
- If $d \neq 0$, then extinction and possible, and σ must not be too small.
- Intermediate time-scale between the first two approaches, but not so fast.



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Proof: ergodic theorem				

Idea of the proof

For simplicity, we will assume that $c(x, y) \equiv c > 0$ and that mutation steps are $\pm \sigma$ with probability 1/2.

Step 1: expected speed of evolution Let ν be a positive measure on \mathcal{X} .

- to simplify the computation, we assume that $b(x) = b_0 + b_1 x$ (OK when the support of ν is small)
- let L^K be the infinitesimal generator of ν^K , and $\phi(\nu) = \frac{\langle \nu, \text{id} \rangle}{\langle \nu, 1 \rangle}$ the "mean trait value function"; then

$$\begin{split} L^{K}\phi(\nu) &= \int \left(\frac{\langle\nu, \mathrm{id}\rangle + \frac{x}{K}}{\langle\nu, 1\rangle + \frac{1}{K}} - \frac{\langle\nu, \mathrm{id}\rangle}{\langle\nu, 1\rangle}\right) (b_{0} + b_{1}x) K\nu(dx) \\ &+ \int \left(\frac{\langle\nu, \mathrm{id}\rangle - \frac{x}{K}}{\langle\nu, 1\rangle - \frac{1}{K}} - \frac{\langle\nu, \mathrm{id}\rangle}{\langle\nu, 1\rangle}\right) c \left(\langle\nu, 1\rangle - \frac{1}{K}\right) K\nu(dx) \\ &= b_{1} \left(\frac{\langle\nu, \mathrm{id}^{2}\rangle}{\langle\nu, 1\rangle} - \frac{\langle\nu, \mathrm{id}\rangle}{\langle\nu, 1\rangle(\langle\nu, 1\rangle + \frac{1}{K})}\right) \\ &= b_{1} \mathrm{Var}(\nu) + O(1/K). \end{split}$$

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Proof: ergodic theorem				

Expected speed of evolution

- Hence, when the support of ν is small, the expected speed of evolution is proportional to the empirical variance of the trait distribution in ν and the gradient of b_1 (= fitness gradient when $c(\cdot, \cdot) \equiv c$)
- To prove that this is true without expectation, one needs to use a version of the ergodic theorem
 → needs (approximate, local) stationarity of increments of φ(ν^K_t).
- What is (approximately) stationary? the centered trait distribution, i.e.

$$\hat{\nu}_t^K := \frac{1}{K} \sum_{i=1}^{N_t^K} \delta_{x_i - \phi(\nu_t^K)}.$$

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- This is close to be Markov (locally).
- \rightsquigarrow need to prove that the support of ν_t^K has small diameter, and that $\hat{\nu}_t^K$ is (nearly) stationary.

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Proof: the neutral case				

Step 2: the neutral case

Assume that $b(x) \equiv b$.

- Then N_t^K is a birth and death Markov process with birth rate $\frac{bn}{K}$ and death rate $\frac{c}{K}n(n-1)$ when $N_t^K = n$.
- $(\hat{\nu}_t^K, t \ge 0)$ is also Markov.
- The invariant distribution of N_t^K is a Poisson distribution conditioned to be positive: $\mu_n^K = \frac{\theta^n}{(e^\theta 1)n!}$, where $\theta = Kb/c$.
- Because of the deterministic limit, large deviations tell us that the exit time of $[\bar{n} - \varepsilon, \bar{n} + \varepsilon]$ is larger that $\exp(C_{\varepsilon}K)$ with high probability.
- Standard coupling arguments: there exists $\gamma > 0$ s.t., for all $K \ge 1$ and for all N_0^K ,

$$\|\mathcal{L}(N_t^K) - \mu^K\|_{TV} \le 2\exp(-\gamma t/\sqrt{K}).$$

 \rightsquigarrow stationary after a time of order \sqrt{K} .

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Proof: the neutral case				

Step 2: the neutral case

A stationary birth and death process is reversible, so after a time $K^{1/2+a}$, the path of $(N_t^K, 0 \le t \le T)$ can be constructed backward in time as $(\tilde{N}_{T-t}^K, 0 \le t \le T)$ where \tilde{N}^K is a Markov birth and death process with the same transitions and started from distribution μ^K .

It is also possible to construct the genealogical relations between individuals backward in time:

- in case of a birth backward in time, a new edge is added to the genealogical tree
- in case of a death backwards in time, pick at random a pair of branches and make them coalesce.

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Proof: the neutral case				

Hence, the ancestral tree of the people present at some (large) time T can be constructed backwards in time in a Markovian way. In particular, if \tilde{R}_t^K is the number of ancestors at time T - t of the individuals living at time T, the process $(\tilde{N}_t^K, \tilde{R}_t^K)_{0 \le t \le T}$ is Markov with transitions

• from (n, k) to (n + 1, k) with rate bn

• from
$$(n,k)$$
 to $(n-1,k)$ with rate $c \frac{n(n-1)}{K} (1 - \frac{k(k-1)}{n(n-1)})$

• from (n,k) to (n-1,k-1) with rate $c \frac{n(n-1)}{K} \frac{k(k-1)}{n(n-1)} = \frac{2c}{K} \frac{k(k-1)}{2}$.

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Note that the ancestral process of a stationary logistic birth and death process if exactly a Kingman coalescent ! (for other processes, this is approximately true since the population density belongs to $[\bar{n} - \varepsilon, \bar{n} + \varepsilon]$ with high probability)

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Proof: the neutral case				

- Mutations can then be added also in a Markovian way, since they occur along ancestral lineages either at coalescence times or at death times of the backward birth and death process for which the coalescing pair contains one of the current ancestral lineages.
- When $\tilde{R}_t^K = k$, this occurs on each ancestral line with rate

$$\frac{2c}{K}(\tilde{N}_t^K - k) \approx 2c\bar{n}$$

• Each mutation produces a trait jump of $\pm \sigma$ with probability 1/2.

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Proof: the neutral case				

Therefore, after rescaling time by 2c/K, the ancestral process is the Kingman coalescent, whose branches are subject to symmetric random walks with rate $K\bar{n}$. This suggests that

Proposition

In the neutral case, and for $t_K \ll K$, $\hat{\nu}_{t_K}^K / \langle \nu_{t_k}^K, 1 \rangle$ scaled in space by $\frac{\sqrt{2}}{\sigma\sqrt{Kn}}$ converges in distribution for the weak topology to the centered distribution of types in the Kingman coalescent with standard Brownian motion along the branches. In addition, the probability that the diameter of $\hat{\nu}_{t_K}^K$ is larger than $\sigma K^{1/2+a}$ converges to 0 for all a > 0.



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Proof: the neutral case			

What we actually need can be checked by hands:

- We want to compute the empirical variance of the traits.
- In the Kingman coalescent with Brownian motion, the computation is easy (Blum, Damerval, Manel, Francois, TPB 2004):
 - in the *n*-coalescent, the empirical variance is given by

$$V_n := \frac{1}{n} \sum_i X_i^2 - \frac{1}{n^2} \left(\sum_j X_j \right)^2 = \frac{1}{n^2} \sum_{i < j} (X_i - X_j)^2,$$

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and $\mathbb{E}[(X_i - X_j)^2] = 2$, so that $V_n \to 1$.

• The computation in the case of the ancestral process of ν_t^K can be done in a very similar way.

Note: this 1st step works for more general models, allowing extinction and for which the limit equation has a single stable equilibrium. One then needs to use quasi-stationary distribution, time-reversed process for quasi-stationary process, and estimates of convergence in the total variation norm to the quasi-stationary distribution (cf. C. ad Villemensia, 2014)

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Proof: the nearly neutral case							

Step 3: the nearly neutral case

We now come back to the non-neutral case. Our goal is to prove that one can approximate the trait distribution by that of a neutral process as long as its support is not too big.

Coupling argument:

- as long as the support of the population is in some small interval with maximum value \bar{b} and minimal value \underline{b} for b(x),
- the process can be coupled with a neutral process with birth rate \underline{b} until the first time a difference appears: at most with rate $(\overline{b} \underline{b})K(\overline{n} + \varepsilon)$;
- after this time, I can obtain a process with more individuals by assuming this new (marked) individual grows a population independently of the first neutral process (no interaction → fewer death events),
- this independent population will never reach $K(\bar{n} + \varepsilon)$ individuals,
- do the same for the next (marked) arrivals of a Poisson process with rate $(\bar{b} - \underline{b})K(\bar{n} + \varepsilon)$, until a time of order K

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Biological context		A stochastic approach	A PDE approach	Third approach			
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Proof: the nearly neutral case							

Step 3: the nearly neutral case

Now, $\overline{b} - \underline{b}$ can be assumed to be of order $\sigma K^{1/2+a}$, and so the assumption $\sigma = o(K^{-5/2})$ means that $(\overline{b} - \underline{b})K^2 \to 0$.

Hence, the probability to have one maked individual in the population converges to 0. It is then easy to check that the empirical variance of the nearly neutral population is very close to the one of the neutral population.



Biological context		A PDE approach	Third approach	Conclusion

Conclusion and comments

- We obtained a third version of the canonical equation of adaptive dynamics on intermediate time scales assuming mutations are small but not rare and that the population is large but no too much.
- The assumption relating σ and K might not be optimal, since we only need the convergence of empirical variances. However, it seems hard to obtain a coupling between the neutral and nearly neutral processes and to contral the difference.
- Evolutionary branching should be studied in this case. However, it seems that the current time scaling leads to a too recent MRCA to hope that evolutionary branching could occur on a short time-scale (it is rather a large deviations event) \rightsquigarrow it is important to find a way to relax the assumption on σ .

Sac