

Index policies for scheduling problems

Maialen Larrañaga

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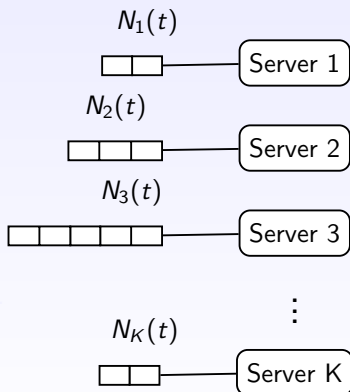
U. Ayesta (CNRS, LAAS), I.M. Verloop (CNRS, IRIT).



YEQT, November 3.

Motivation

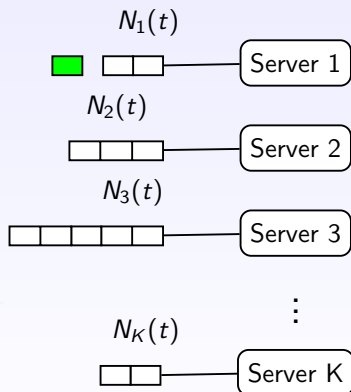
Optimal class selection:



- Arrivals
- Loss/Abandonments
- Service completion

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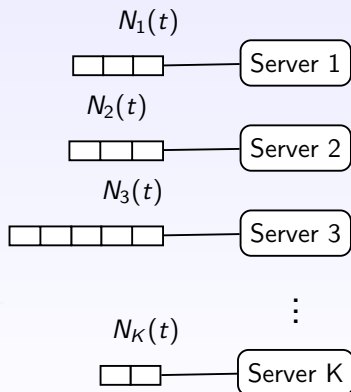
Optimal class selection:






- Green square: Arrivals
- Red square: Loss/Abandonments
- Blue square: Service completion

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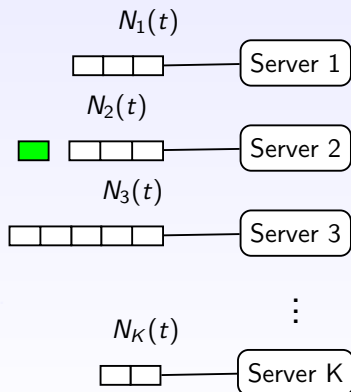
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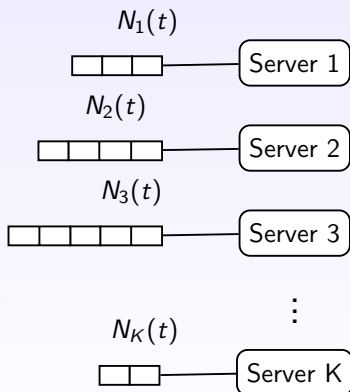
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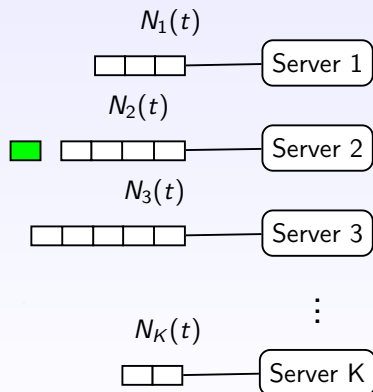
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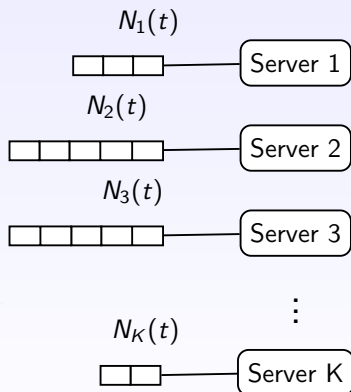
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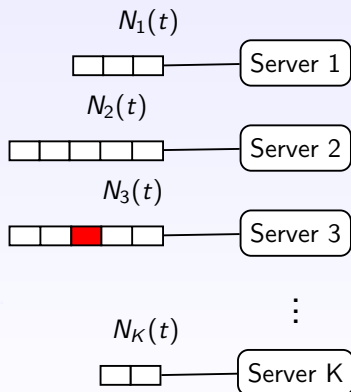
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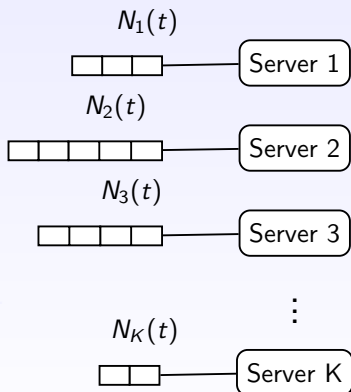
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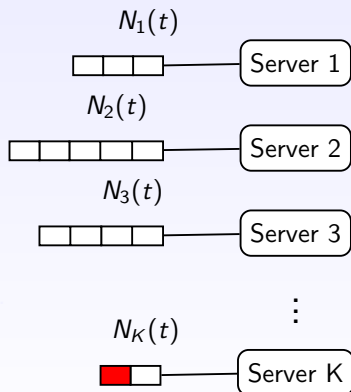
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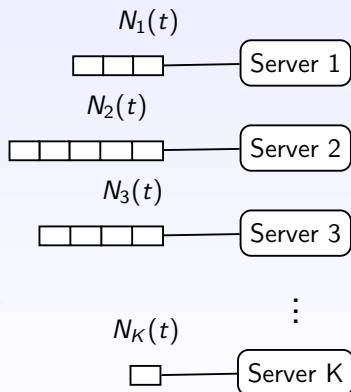
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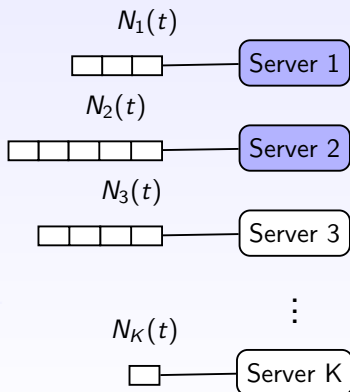
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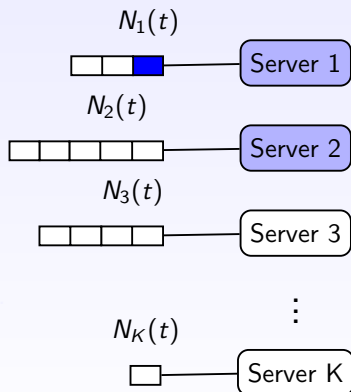


Which M classes activate?




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-  Service completion

Motivation

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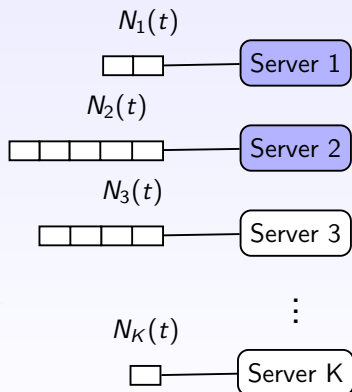


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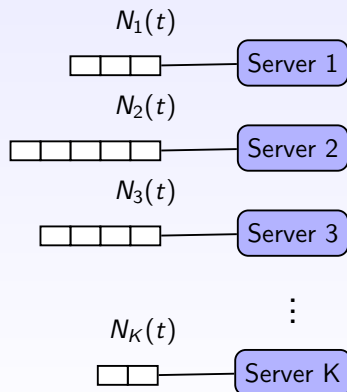
} Which M classes activate?




Type of problems

- Call centers.
- Wireless downlink problem.

Motivation

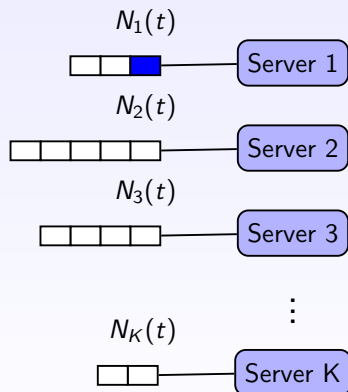
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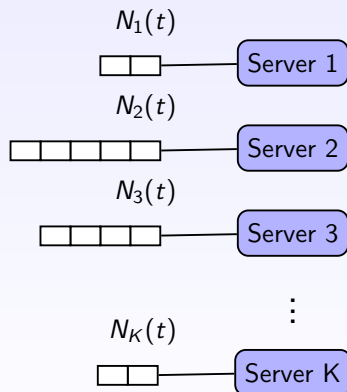
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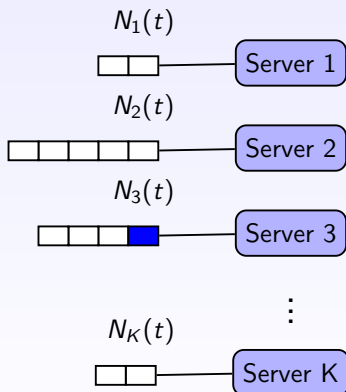
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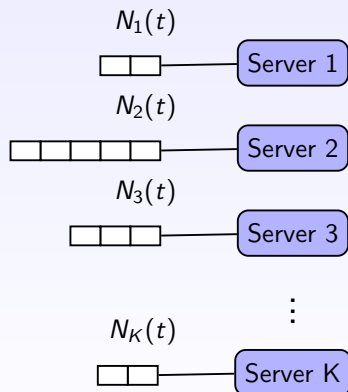
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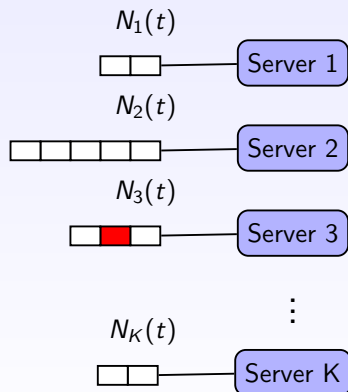
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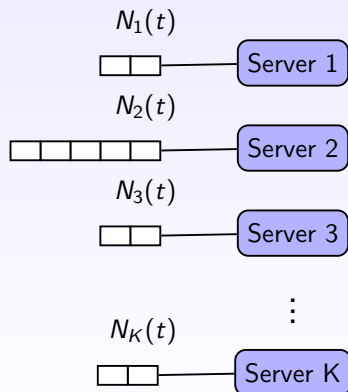
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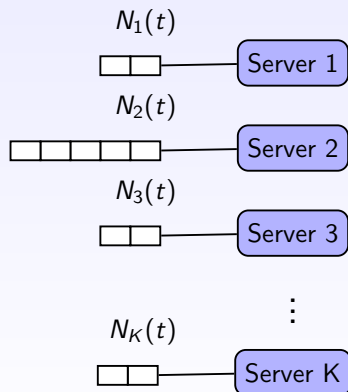





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Optimal load balancing:

To which M servers
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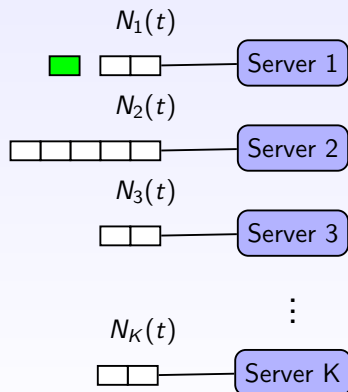





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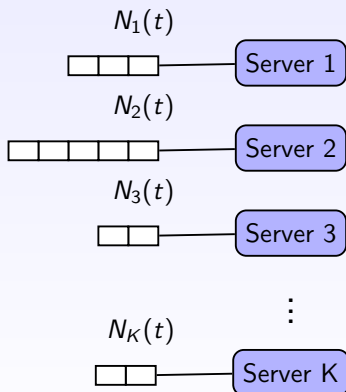





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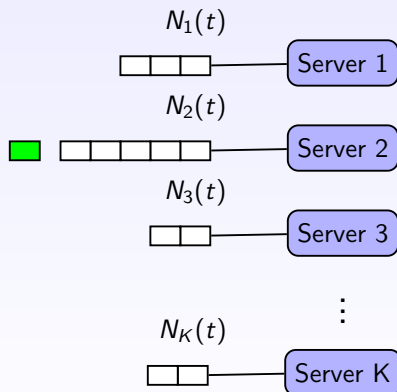





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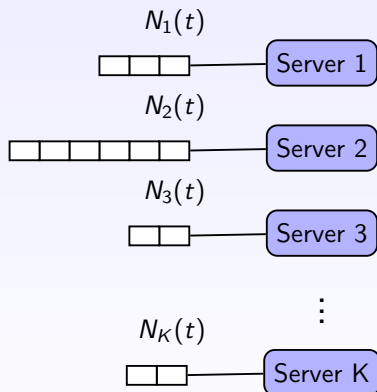





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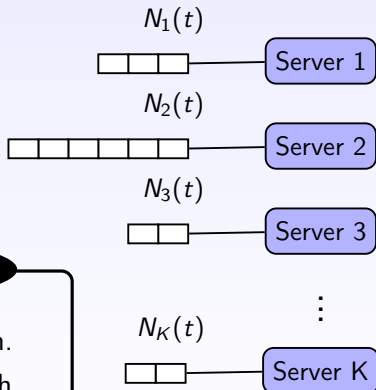
Motivation

Optimal load balancing:

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Type of problems

- Power-aware server farm.
- Routing+Admission with impatience.



Objective

The objective is to find the **scheduling policies** that **minimize** the average-cost criteria

$$\sum_{k=1}^K \mathbb{E} \left[C_k(N_k^\phi, S_k^\phi(N^\phi)) \right]$$

where $C_k(\cdot, \cdot)$ is the cost function under policy ϕ .

- N_k^ϕ number of class-k customers in system.
- $S_k^\phi(\vec{N}) = 0$, if ϕ prescribes to be passive, 1 otherwise.
- $\sum_k S_k^\phi(\vec{N}(t)) \leq M$.

How to solve?

1.-Heuristic: stochastic indices

Lagrangian relaxation

Original problem:

$$\min_{\phi} \sum_{k=1}^K \mathbb{E} \left[C_k(N_k^{\phi}, S_k^{\phi}(N^{\phi})) \right]$$

$$\sum_{k=1}^K S_k^{\phi}(\vec{N}^{\phi}(t)) \leq M$$

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Relax the constraint:

$$\min_{\phi} \sum_{k=1}^K \mathbb{E} \left[C_k(N_k^{\phi}, S_k^{\phi}(N^{\phi})) \right]$$

$$\mathbb{E} \left(\sum_{k=1}^K S_k^{\phi}(N^{\phi}) \right) \leq M$$

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Relaxed problem:

$$\min_{\phi} \sum_{k=1}^K \mathbb{E} \left[C_k(N_k^{\phi}, S_k^{\phi}(N^{\phi})) \right] - \mathbf{w} \left(\mathbf{M} - \mathbb{E} \left(\sum_{k=1}^K \mathbf{S}_k^{\phi}(N^{\phi}) \right) \right)$$

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K-dimensional problem \implies **unidimensional problem**

$$\min_{\phi} \mathbb{E} \left[C(N^{\phi}, S^{\phi}(N^{\phi})) \right] - \mathbf{w} \mathbb{E} \left(\mathbf{1}_{S^{\phi}(N^{\phi})=0} \right)$$

Heuristic for original problem

Index type of policies are optimal for relaxed problem.

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The solution to relaxation **NOT feasible** for original problem.



Need to define a **heuristic** for original model.

Example

$$\text{Class 1} \rightarrow W_1(N_1) = 5N_1,$$

$$\text{Class 2} \rightarrow W_2(N_2) = 4,$$

$$\text{Class 3} \rightarrow W_3(N_3) = 2N_3^2,$$

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Set $W = 3$, then solution of relaxed

State	$W_1(N_1)$	$W_2(N_2)$	$W_3(N_3)$	Policy
$N(0) = (1, 1, 1)$	5	4	2	Serve Class 1 and 2

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Heuristic

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Outline

- 1 Lagrangian Relaxation
- 2 Fluid Model of Relaxed Problem
- 3 Case studies
 - Scheduling a multi-class queue with impatient users
 - Routing/blocking in a power-aware server-farm
- 4 Conclusion

Whittle's Index: relaxed model

$$\min_{\phi} \sum_{k=1}^K \left(\mathbb{E} \left[C_k(N_k^{\phi}, S_k^{\phi}(N^{\phi})) \right] - W \left(M - \mathbb{E} \left(\sum_{k=1}^K S_k^{\phi}(N^{\phi}) \right) \right) \right)$$

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Where W serves as *subsidy for passivity* or penalization for activity.
Drop dependency on k , classes are independent of each other.

$$\min_{\phi} \left(\mathbb{E} \left[C(N^{\phi}, S^{\phi}(N^{\phi})) \right] - W \mathbb{E} \left(\mathbb{1}_{S^{\phi}(N^{\phi})=0} \right) \right)$$

for each class k compute $W_k(N_k)$, amount of subsidy so as indifferent of the action in state N_k .

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- Consider Birth-and-Death processes.

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Proposition: Whittle's index

$$W(n) = \frac{\mathbb{E}(C(N^n, S^n(N^n))) - \mathbb{E}(C(N^{n-1}, S^{n-1}(N^{n-1})))}{\sum_{m=0}^n \pi^n(m) - \sum_{m=0}^{n-1} \pi^{n-1}(m)},$$

where $\pi^n(m)$ is the steady-state distribution under threshold policy n .

Heuristic

- Solution of the relaxed problem is to serve all classes such that

$$W_k(N_k) \geq W.$$

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Disadvantages of Whittle's index:

- **Indexability** and **monotonicity** might be hard to prove.
- Very hard to obtain **qualitative insights**.

Fluid model of Relaxed Problem

Transition of stochastic model:

$$q_k^a(N_k, N_k + 1) = b_k^a(N_k), \quad q_k^a(N_k, N_k - 1) = d_k^a(N_k),$$

where $a \in \{0, 1\}$.

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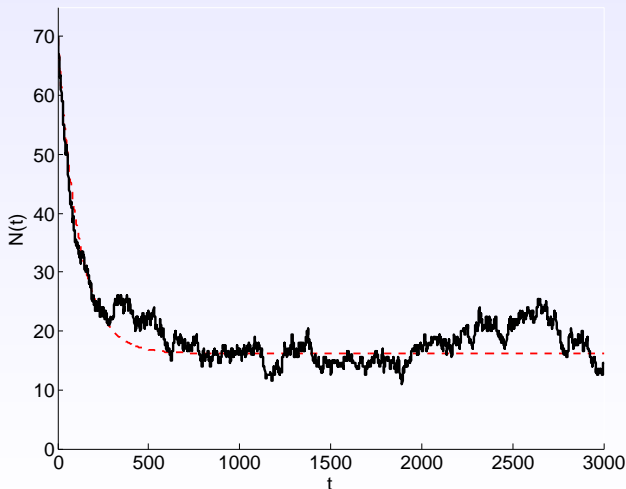
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Approximate the relaxed stochastic model by the deterministic:

$$\frac{dm^u(t)}{dt} = (1 - s^u(t))f^0(m^u(t)) + s^u(t)f^1(m^u(t)),$$

where u is the fluid control that determines $s^u(t) \in \{0, 1\}$.

On steady-state the stochastic process resembles the fluid approximation



Objective of fluid approximation

Objective: find u so as to minimize **bias-optimal** criteria:

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$$\min_{s(t)} \int_0^{\infty} (C(m(t), s(t)) - \mathbf{W}(1 - s(t))) - EC^*(W) dt$$

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where $EC^*(W)$ is the cost at equilibrium, that is,

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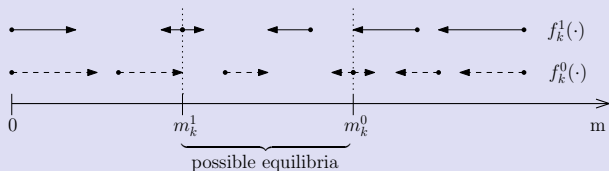
$$EC^*(W) := (1 - s^*)C(m^*, 0) + s^*C(m^*, 1) - W(1 - s^*).$$

and the system evolves as the following ODE

$$\frac{dm^u(t)}{dt} = (1 - s^u(t))f^0(m^u(t)) + s^u(t)f^1(m^u(t)),$$

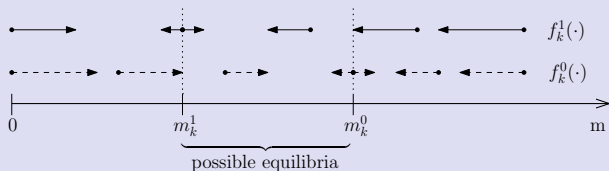
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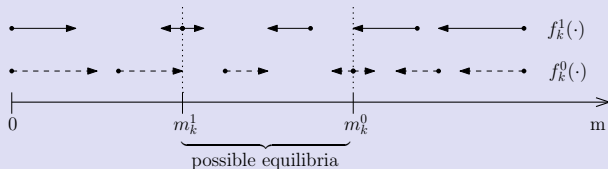


then, $s(t) = 1$, if $w(m) \geq W$ and $s(t) = 0$ otherwise. Where

$$w(m) = C(m, 0) - C(m, 1) + \begin{cases} w^{(1)}(m) & \text{if } m < m^1, \\ w^{(2)}(m) & \text{if } m \in [m^1, m^0], \\ w^{(3)}(m) & \text{if } m > m^0, \end{cases}$$

Proposition: an optimal solution

Let all possible equilibria be in $[m^1, m^0]$,



$$w^{(1)}(m) = (f^1(m) - f^0(m)) \frac{C(m, 1) - C(m^1, 1)}{f^1(m)},$$

$$w^{(2)}(m) = \frac{(f^1(m) - f^0(m)) \left(f^0(m) \frac{dC(m, 1)}{dm} - f^1(m) \frac{dC(m, 0)}{dm} \right)}{f^0(m) \frac{df^1(m)}{dm} - f^1(m) \frac{df^0(m)}{dm}},$$

$$w^{(3)}(m) = (f^1(m) - f^0(m)) \frac{C(m, 0) - C(m^0, 0)}{f^0(m)}.$$

Fluid index policy

- Monotonicity is a consequence of $w(\cdot)$ being non-decreasing.
- Indexability is immediate.

Definition: Fluid index policy

Assume the system's state is $\vec{N}(t) = \vec{n}$, the fluid index policy prescribes to serve the M bandits having currently the highest non-negative fluid index $w_k(n_k)$.

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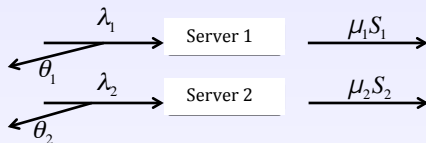
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Advantages:

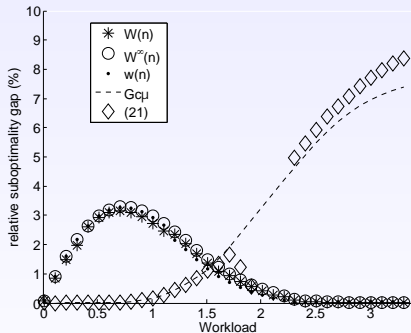
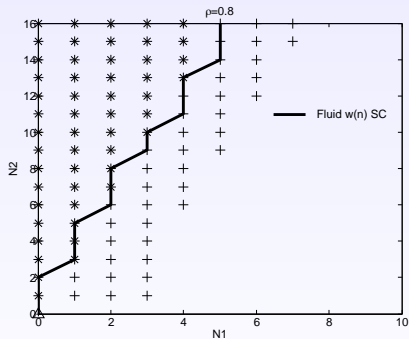
- non-decreasingness of $w(\cdot)$ easy to check.
- Fluid index in close-form expression.

scheduling a multi-class queue with impatient users

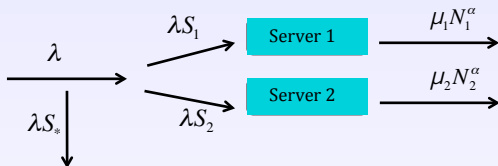


- Only one server can be activated.
- Objective: find the policy to minimize cost of holding + cost for abandoning.
- We compute $W_k(N_k)$ numerically,
- We obtain $w_k(n_k)$ in closed form expression.

Example 1



Routing/blocking in a power-aware server-farm



- We can only dispatch to one queue.
- Speed scaling rule applied: $d_k^a(N_k) = \mu_k N_k^\alpha$.
- Objective: find the policy to minimize cost of holding + cost for rejection + power consumption.
- We compute $W_k(N_k)$ numerically,
- We obtain $w_k(n_k)$ in closed form expression.

Example 2

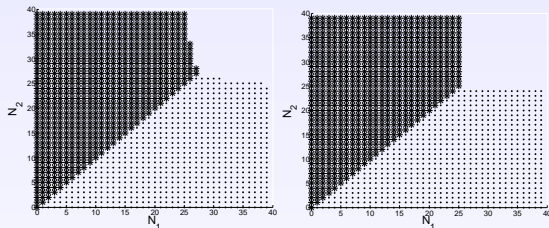


Figure: . (*) priority to class 1 (class 2). White area users blocked.

ρ	0.1	0.9	2
Fluid index	0.08704×10^{-7}	0.0821×10^{-7}	0.06099×10^{-7}
Whittle's index	0.08704×10^{-7}	0.0821×10^{-7}	0.06099×10^{-7}

Conclusion

- Derive an expression for the Whittle index in BD systems.
- Develop a new method: fluid index
 - Monotonicity easy to verify.
 - Closed form expression of W .

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Perspectives:

- Get sufficient conditions for the fluid index to be non-decreasing.
- Is the fluid index asymptotically optimal?
- When do the Whittle and the fluid index coincide?

Thank you!