

# Gibbs under stochastic dynamics?

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## Abstract

This paper is a mini-overview of some recent results on the evolution of Ising-spin systems under Glauber spin-flip dynamics, in particular, the question whether Gibbsianness is preserved, lost or recovered during the dynamics. Examples of all three scenarios are given, with an explanation of what drives the behavior. Some open problems are formulated as well.

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# 1 Introduction

## 1.1 Main question

The question that we address in this paper is the following. Consider Ising spins on  $\mathbb{Z}^d$  evolving under a Glauber spin-flip dynamics from an *initial* Gibbs measure  $\mu$  towards a *final* Gibbs measure  $\nu$  ( $\neq \mu$ ). Is it possible that along the way the Gibbs property is

- preserved?
- lost?
- recovered?

The answer to this question turns out to be yes in all three cases. The goal of this paper is to give examples with explanation. We will see that these examples are natural and typical. The results to be described below are taken from van Enter, Fernández, den Hollander and Redig [3], and rely on the work by C. Maes and C. Netocný [8]. For proofs we refer the reader to these papers.

In statistical physics the above three scenarios correspond to preservation, loss or recovery of *temperature* in a *non-equilibrium* setting (where the dynamics can be viewed as a transformation acting on the probability law of the Ising spins). It is well known that such behavior occurs in an *equilibrium* setting (under renormalization-type transformations). For an extensive account of the latter up to 1993, we refer the reader to the review paper by van Enter, Fernández and Sokal [2]. Later developments are described in van Enter [1], Fernández [5], van Enter, Maes and Shlosman [4], and Maes [7].

## 1.2 Gibbs measures

Let  $\Omega = \{-1, +1\}^{\mathbb{Z}^d}$  be the Ising-spin configuration space.

**Definition 1.2.1** *A probability measure  $\rho$  on  $\Omega$  is Gibbs if it has the DLR-property (Dobrushin-Lanford-Ruelle), i.e.,*

$$\rho(\sigma_\Lambda | \eta_{\Lambda^c}) = \frac{1}{Z_{\eta_{\Lambda^c}}} e^{-H(\sigma_\Lambda \vee \eta_{\Lambda^c})} \quad \forall \sigma, \eta \in \Omega, \forall \Lambda \subset\subset \mathbb{Z}^d, \quad (1.2.1)$$

with a Hamiltonian  $H: \Omega \mapsto \mathbb{R}$  of the form

$$H(\omega) = \sum_{A \subset\subset \mathbb{Z}^d} U_A(\omega), \quad \omega \in \Omega, \quad (1.2.2)$$

where  $(U_A)_{A \subset\subset \mathbb{Z}^d}$  are interaction potentials satisfying

$$\sup_{\omega \in \Omega} \sum_{\substack{A \subset\subset \mathbb{Z}^d \\ A \ni x}} |U_A(\omega)| < \infty \quad \forall x \in \mathbb{Z}^d. \quad (1.2.3)$$

Here,  $\subset\subset$  stands for finite subset,  $\sigma_\Lambda$  and  $\eta_{\Lambda^c}$  are the restrictions of  $\sigma$  to  $\Lambda$  and  $\eta$  to  $\Lambda^c$ , respectively,  $\sigma_\Lambda \vee \eta_{\Lambda^c}$  denotes their joining,  $Z_{\eta_{\Lambda^c}}$  is the partition sum in  $\Lambda$  given  $\eta$  outside  $\Lambda$ , while  $U_A(\omega)$  depends on  $\omega_A$  only. The uniform absolute summability condition in (1.2.3) implies the *uniform non-nullness* and the *quasi-locality* that are characteristic of Gibbs measures.

### 1.3 Glauber spin-flip dynamics

We consider the following situation:

1. At time  $t = 0$ , start from a translation-invariant Gibbs measure  $\mu$  with finite-range interaction and with inverse temperature  $\beta_\mu$ .
2. At times  $t > 0$ , run a Glauber dynamics with spin-flip rates that are finite-range, translation-invariant and strictly positive. This dynamics has as equilibrium *at least one* translation-invariant (reversible) Gibbs measure  $\nu$  with finite-range interaction and with inverse temperature  $\beta_\nu$ .

Let  $\mu_t$  be the measure evolved at time  $t$ . Then in good situations we have

$$\mu_0 = \mu \quad \text{and} \quad \mu_t \Rightarrow \nu \text{ as } t \rightarrow \infty. \quad (1.3.1)$$

A priori,  $\nu$  may depend on  $\mu$ . Below we will only consider *high-temperature dynamics*, i.e.,  $0 \leq \beta_\nu \ll 1$ , in which case  $\mu_t$  converges to a unique  $\nu$ . We are interested in finding out under what conditions

$$\mu_t \text{ is Gibbs for all/some/no } t > 0. \quad (1.3.2)$$

Inverse temperature can be viewed as a norm for the interaction.

### 1.4 Gibbs versus non-Gibbs

A necessary and sufficient condition for a probability measure not to be Gibbs is the *existence of a bad configuration*.

**Definition 1.4.1** *A configuration  $\eta \in \Omega$  is called bad for a probability measure  $\rho$  on  $\Omega$  if there exist  $\epsilon > 0$  and  $x \in \mathbb{Z}^d$  such that:*

$$\begin{aligned} \forall \Lambda \ni x, \Lambda \subset\subset \mathbb{Z}^d \quad \exists \Gamma \supset \Lambda, \Gamma \subset\subset \mathbb{Z}^d \quad \exists \xi, \zeta \in \Omega : \\ \left| \rho_\Gamma(\sigma(x) \mid \eta_{\Lambda \setminus \{x\}} \vee \xi_{\Gamma \setminus \Lambda}) - \rho_\Gamma(\sigma(x) \mid \eta_{\Lambda \setminus \{x\}} \vee \zeta_{\Gamma \setminus \Lambda}) \right| > \epsilon, \end{aligned} \quad (1.4.1)$$

where  $\rho_\Gamma$  is  $\rho$  restricted to  $\Gamma$ .

The inequality in (1.4.1) signals the failure of quasi-locality in  $\eta$ .

The set of bad configurations has  $\rho$ -measure 0 or 1 when  $\rho$  is ergodic.

## 2 Main theorems and a criterion for Gibbsianness

Below, when we write “for all  $\nu$ ” we mean “for all Glauber spin-flip dynamics whose invariant measure is  $\nu$ ”.

## 2.1 Main theorems

**Theorem 2.1.1** *For all  $\mu, \nu$  there exists  $t_0 = t_0(\mu, \nu) > 0$  such that  $\mu_t$  is Gibbs for all  $t \in [0, t_0)$ .*

This says that *Gibbsianness is preserved for small times*.

Intuition: The set of sites where a spin-flip has occurred consists of “small islands” that are far apart in a “sea” of sites where no spin-flip has occurred. Consequently, sites that are far apart have disjoint histories with a high probability, implying (in a percolation-type fashion) that there are no bad configurations.

**Theorem 2.1.2** *For all  $\mu, \nu$  such that  $0 \leq \beta_\mu, \beta_\nu \ll 1$ :  $\mu_t$  is Gibbs for all  $t \geq 0$ .*

This says that *Gibbsianness is preserved for all times when both  $\mu, \nu$  have a high temperature*.

Intuition: The time-evolved measure stays in the regime where no phase transition occurs, implying that there are no bad configurations.

**Theorem 2.1.3** *Assume that:*

(i)  $1 \ll \beta_\mu < \infty$ , with  $\mu$  the plus-phase of the standard Ising Hamiltonian with magnetic field  $h$ .

(ii)  $0 \leq \beta_\nu \ll 1$ .

*Under these assumptions:*

I. If  $h = 0$ , then there exists  $0 < t_1 = t_1(\mu, \nu) < \infty$  such that  $\mu_t$  is not (!) Gibbs for all  $t \in [t_1, \infty)$ .

II. If  $h > 0$ , then there exists  $0 < t_2 = t_2(\mu, \nu) < \infty$  such that  $\mu_t$  is Gibbs for all  $t \in [t_2, \infty)$ .

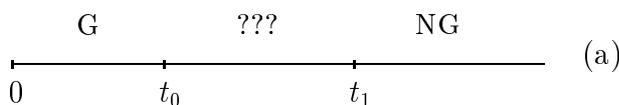
III. Suppose that  $d \geq 3$ . If  $0 < h \ll 1$ , then there exist  $0 < t_3 = t_3(\mu, \nu) < t_4 = t_4(\mu, \nu) < \infty$  such that  $\mu_t$  is not (!) Gibbs for all  $t \in [t_3, t_4)$ .

This says that *Gibbsianness may get lost and may get recovered when the system is heated up from a low temperature to a high temperature*. Apparently, the magnetic field plays an important role in determining which scenario occurs.

Intuition: Not immediate. See Section 3.

The result in Theorem 2.1.3 is quite remarkable, because the regime of exponentially fast convergence to a high-temperature Gibbs measure a priori seems unproblematic.

Figure 1 summarizes the statements in Theorem 2.1.3 (in combination with those in Theorems 2.1.1 and 2.1.2). We believe that picture (b) holds for all  $d \geq 2$  and  $h > 0$ , but the proof requires the stated restrictions.



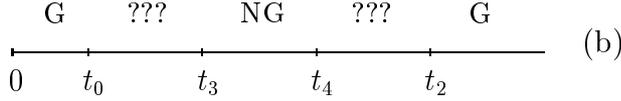


Fig. 1: (a)  $h = 0$ ; (b)  $d \geq 3$ ,  $0 < h \ll 1$ .

## 2.2 A criterion for Gibbsianness

Let  $\sigma_t$  be the spin configuration at time  $t$ . Consider the pair

$$(\sigma_0, \sigma_t), \quad (2.2.1)$$

and let  $\hat{\mu}_t$  denote its joint distribution on  $\Omega \times \Omega$ . The left marginal is  $\mu$ , the right marginal is  $\mu_t$ .

Suppose that  $\hat{\mu}_t$  is Gibbs (this is not obvious!). Then it has joint Hamiltonian  $H_t(\sigma, \eta)$  given by

$$e^{-H_t(\sigma, \eta)} = e^{-H_\mu(\sigma)} p_t(\sigma, \eta), \quad (2.2.2)$$

or

$$H_t(\sigma, \eta) = H_\mu(\sigma) - \log p_t(\sigma, \eta), \quad (2.2.3)$$

where  $p_t(\sigma, \eta)$  is the transition kernel of the spin-flip dynamics. Here, the last term has to be *properly interpreted* in the sense of a formal sum of  $t$ -dependent interaction potentials, like in (1.2.2) (this is not obvious!). For  $\eta \in \Omega$ , let

$$\mathcal{G}(H_t^\eta) \quad (2.2.4)$$

be the set of Gibbs measures associated with the Hamiltonian  $H_t^\eta(\sigma) = H_t(\sigma, \eta)$ , where  $\eta$  is fixed and  $\sigma$  is running. A key criterion in our analysis is the following:

**Proposition 2.2.1** (Fernández and Pfister [6]) *Fix  $t \geq 0$ . Under the assumption that  $\hat{\mu}_t$  is Gibbs:*

1. *If  $|\mathcal{G}(H_t^\eta)| = 1$  for all  $\eta \in \Omega$ , then  $\mu_t$  is Gibbs.*
2. *For monotone interactions, if  $|\mathcal{G}(H_t^\eta)| \geq 2$  for some  $\eta \in \Omega$ , then  $\eta$  is a bad configuration for  $\mu_t$ , and hence  $\mu_t$  is not Gibbs.*

In part 2, the non-Gibbsianness comes from the presence of a phase transition in  $\sigma$  for fixed  $\eta$ . (If we look at the marginal  $\mu_t$  at time  $t$ , then we are summing out over the marginal  $\mu_0$  at time 0.) The restriction to monotone interactions is believed to be redundant.

The idea is to use the above criterion for a *high-temperature dynamics* ( $0 \leq \beta_\nu \ll 1$ ), for which it is possible to make sense of the *dynamical part* of  $H_t^\eta$ , i.e., the last term in the right-hand side of (2.2.3), as is shown in Maes and Netocný [8] with the help of a *space-time cluster expansion*.

For the proof of Theorems 2.1.2 and 2.1.3 we refer to van Enter, Fernández, den Hollander and Redig [3]. In Section 3 we consider the case  $\beta_\nu = 0$ , i.e., *infinite-temperature dynamics*. It turns out that this case already exhibits all the relevant features.

### 3 Sketch of proof for $\beta_\nu = 0$

#### 3.1 Joint Hamiltonian

Consider the evolution of  $\mu$  under a *product dynamics* where each spin flips independently at rate 1. Since under this dynamics the conditional probability of the event  $\{\sigma_t(x) = \eta(x)\}$  given the event  $\{\sigma_0(x) = \sigma(x)\}$  is

$$\begin{aligned} \frac{1}{2}(1 + e^{-2t}) & \text{ if } \sigma(x) = \eta(x), \\ \frac{1}{2}(1 - e^{-2t}) & \text{ if } \sigma(x) \neq \eta(x), \end{aligned} \tag{3.1.1}$$

the joint Hamiltonian in (2.2.3) is given by

$$H_t(\sigma, \eta) = H_\mu(\sigma) - \sum_x [h_t \eta(x)] \sigma(x) \tag{3.1.2}$$

with

$$h_t = \frac{1}{2} \log \frac{1 + e^{-2t}}{1 - e^{-2t}}. \tag{3.1.3}$$

(Note that constants do not matter in the Hamiltonian.) The *dynamical magnetic field*  $h_t$  is strictly decreasing in  $t$  with  $h_0 = \infty$  and  $h_\infty = 0$ , corresponding to full correlation between  $\sigma$  and  $\eta$  at time  $t = 0$ , respectively, no correlation at time  $t = \infty$ .

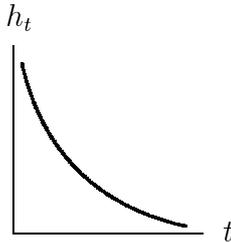


Fig. 2:  $t \mapsto h_t$ .

#### 3.2 High- and low-temperature initial measure

- $0 < \beta_\mu \ll 1$ :

$H_\mu$  has no phase transition. Since, for any  $\eta$  and  $t$ ,  $H_t^\eta$  differs from  $H_\mu$  only in the single-site interaction, it also has no phase transition. Hence Proposition 2.2.1, part 1, applies.

- $1 \ll \beta_\mu < \infty$ :

We consider the plus-phase of the standard Ising Hamiltonian with magnetic field  $h$ , i.e.,

$$H_\mu(\sigma) = -\beta \sum_{x \sim y} \sigma(x)\sigma(y) - h \sum_x \sigma(x) \tag{3.2.1}$$

with  $\beta = \beta_\mu$ . Then the joint Hamiltonian in (3.1.2) reads

$$H_t^\eta(\sigma) = -\beta \sum_{x \sim y} \sigma(x)\sigma(y) - \sum_x [h + h_t \eta(x)] \sigma(x). \quad (3.2.2)$$

There are four subcases:

### 3.2.1 $\mu_t$ Gibbs for small $t$

For small  $t$ ,  $h_t$  is large and, for given  $\eta$ , forces  $\sigma$  in the direction of  $\eta$ . Rewrite (3.2.2) as

$$H_t^\eta(\sigma) = \sqrt{h_t} \tilde{H}_t^\eta(\sigma) \quad (3.2.3)$$

with

$$\tilde{H}_t^\eta(\sigma) = -\frac{\beta}{\sqrt{h_t}} \sum_{x \sim y} \sigma(x)\sigma(y) - \sum_x \left[ \frac{h}{\sqrt{h_t}} + \sqrt{h_t} \eta(x) \right] \sigma(x). \quad (3.2.4)$$

For small  $t$ , the last term in the right-hand side of (3.2.4) is the dominant interaction (independently of  $\eta$ , not of  $\beta, h$ ). Therefore  $\tilde{H}_t^\eta$  has the unique ground state  $\sigma = \eta$ . Consequently,  $H_t^\eta$  in (3.2.3) satisfies the Dobrushin condition for large enough inverse temperature  $\sqrt{h_t}$ . Hence Proposition 2.2.1, part 1, applies.

### 3.2.2 $h > 0$ : $\mu_t$ Gibbs for large $t$

For large  $t$ ,  $h_t$  is small and cannot overrule the effect of  $h > 0$ . Rewrite (3.2.2) as

$$H_t^\eta(\sigma) = \sqrt{\beta} \tilde{H}_t^\eta(\sigma) \quad (3.2.5)$$

with

$$\tilde{H}_t^\eta(\sigma) = -\sqrt{\beta} \sum_{x \sim y} \sigma(x)\sigma(y) - \sum_x \left[ \frac{h}{\sqrt{\beta}} + \frac{h_t}{\sqrt{\beta}} \eta(x) \right] \sigma(x). \quad (3.2.6)$$

For large  $t$ , the middle term in the right-hand side of (3.2.6) is the dominant interaction (independently of  $\eta$ , not of  $\beta, h$ ). Therefore  $\tilde{H}_t^\eta$  has the unique ground state  $\sigma \equiv h/|h|$ . Consequently,  $H_t^\eta$  in (3.2.5) satisfies the Dobrushin condition for large enough inverse temperature  $\sqrt{\beta}$ . Hence Proposition 2.2.1, part 1, applies.

### 3.2.3 $h = 0$ : $\mu_t$ not Gibbs for large $t$

Pick  $\eta = \eta_a$ , the alternating configuration. For large  $t$ ,  $h_t$  is small and

$$H_t^{\eta_a}(\sigma) = -\beta \sum_{x \sim y} \sigma(x)\sigma(y) - h_t \sum_x \eta_a(x)\sigma(x) \quad (3.2.7)$$

has two ground states,  $\sigma \equiv +1$  and  $\sigma \equiv -1$ , because the last term in (3.2.7) is neutral in selecting them. By an application of Pirogov-Sinai theory, it follows that  $H_t^{\eta_a}$  has a phase transition for large enough inverse temperature  $\beta$ , so  $\eta_a$  is a bad configuration. Hence Proposition 2.2.1, part 2, applies.

### 3.2.4 $d \geq 3$ , $0 < h \ll 1$ : $\mu_t$ not Gibbs for intermediate $t$

A rough argument goes as follows. For intermediate  $t$ ,  $h$  and  $h_t$  are of the same order (both small). Therefore we can find a configuration  $\eta^*$  such that the external magnetic field in (3.2.2),

$$x \mapsto h + h_t \eta^*(x), \quad (3.2.8)$$

is “zero on average”, i.e., its average over a large box tends to zero as the box tends to  $\mathbb{Z}^d$  (for instance,  $h_t/h = 2$  and  $\eta^*$  is a periodic repetition of  $+1 - 1 - 1 - 1$ ). In that case  $H_t^{\eta^*}$  has two ground states,  $\sigma \equiv +1$  and  $\sigma \equiv -1$ , because the magnetic field is neutral in selecting them. By an application of Pirogov-Sinai theory, it follows that  $H_t^{\eta^*}$  has a phase transition for large enough inverse temperature  $\beta$ , so  $\eta^*$  is a bad configuration. Hence Proposition 2.2.1, part 2, applies.

To make the above argument precise, we need the following. As shown by Zahradnik [10], in  $d \geq 3$  the *random field Ising model* at large enough inverse temperature has a phase transition when the random field is small and zero on average. This phase transition occurs for a set of random fields with measure 1 under the Bernoulli measure. From this we conclude that  $\eta^*$  can be drawn from a set of configurations with measure 1 under the Bernoulli measure (not  $\mu_t!$ ). This in turn guarantees that  $\eta^*$  exists.

## 4 Open problems

Some challenges for the future are:

1. What is the physical origin of the transition from Gibbs to non-Gibbs? In van Enter, Fernández, den Hollander and Redig [3] it is suggested that a *nature versus nurture* transition may be responsible, namely, a crossover from a situation where fluctuations are dominated by the initial measure (small times) to a situation where fluctuations are dominated by the dynamics (large times). This suggestion has not yet been properly investigated.
2. In the case where  $\mu_t$  is Gibbs for all  $t \geq 0$ , what can we say about the *trajectory*  $t \mapsto H_{\mu_t}$ ? For instance, how does  $H_{\mu_t}$  converge to  $H_\nu$ ? The space-time cluster expansion developed in Maes and Netocny [8] should serve as the starting point for such an analysis.
3. What about  $1 \ll \beta_\nu < \infty$ , i.e., *low-temperature dynamics*? Here, one of the main obstacles is to make sense of the dynamical part of  $H_t^\eta$ , i.e., the last term in the right-hand side of (2.2.3). Probably many different scenarios are possible, and *metastability phenomena* are to be expected.
4. Is it true that  $\mu_t$  is *weakly Gibbs* for all  $t \geq 0$  always? Or even *almost Gibbs* for all  $t \geq 0$  always? <sup>1</sup>

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<sup>1</sup>Weakly Gibbs means that  $\mu_t$  has an absolutely summable interaction potential for a set of configurations of measure 1 w.r.t.  $\mu_t$ . Almost Gibbs means that the set of bad configurations for  $\mu_t$  has measure 0 w.r.t.  $\mu_t$ . This is stronger than weakly Gibbs.

5. What about other types of dynamics? It was shown by Le Ny and Redig [9] that Gibbsianness is preserved for short times under an *arbitrary reversible local dynamics*, i.e., Theorem 2.1.1 generalizes fully. Does a similar type of behavior as described in Theorems 2.1.2 and 2.1.3 hold for the lattice gas under Kawasaki dynamics at high temperature? Infinite-temperature Kawasaki dynamics corresponds to the exclusion process. Thus, we would first need to understand the evolution of Gibbs measures under the exclusion process and we would afterwards need to carry out an expansion for weak attraction on top of exclusion. However, the trouble is that exclusion is not a weak interaction itself. “Glassy dynamics” is an even greater challenge.
6. What about spins taking values in a *continuous* space? This question is addressed in the paper by Dereudre and Roelly appearing elsewhere in this volume, where for interacting diffusions a generalization of Theorems 2.1.1 and 2.1.2 is achieved. Phase transitions for continuous systems are typically hard to handle. A criterion like Proposition 2.2.1 is so far absent in the continuous setting. As is clear from Section 3, this criterion is the key tool in establishing the results described in Section 2.

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