

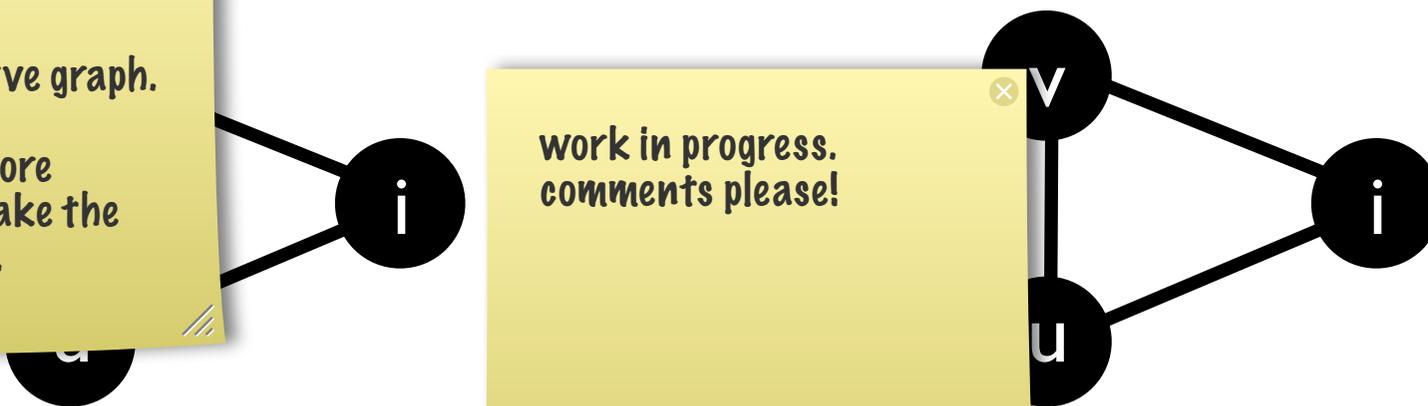
# *The blessing of dimensionality for sparse Stochastic Blockmodels.*

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graph model: high degree hard.

inference: observe graph. edges are like observations, more observations make the problem easier...

work in progress. comments please!



**Disclaimer:  
This is work  
in progress.**



# Abstract

- What is the model? What are we estimating?
- Current literature
  - Low-dimensional
  - Networks not transitive
- “Highest dimensional model”
  - Transitive
  - Easier estimation
  - Faster, local algorithms.

# Inference for clustering

- Presume that graph is observed.
- Sampled from a distribution in a known class.
- What is estimable?
- Certain models lead to clusters. Can we estimate the corresponding parameters?

# Exchangeable Random Graphs and Latent space models (Hoff et al 2002)

Observe:  $A = \{0, 1\}^{n \times n}$  undirected, unweighted.

Edges conditionally independent.

$$P(A|Z) = \prod_{u < v} P(A|Z_u, Z_v)$$

Wish to estimate latent variables

$$Z_1, \dots, Z_n$$

# Stochastic Blockmodels (Holland et al 1983)

are a type of exchangeable random graph.

Stochastic Blockmodels (SBMs) say class memberships

$Z_i \in \{1, \dots, K\}$  yield

$$P(A_{uv} = 1 | Z_u, Z_v) = \Theta_{Z_u, Z_v}$$

$$\text{for } \Theta \in [0, 1]^{K \times K}$$

Large diagonal elements in Theta makes communities.  
Estimating  $Z$  = clustering

Several have studied estimators for  $Z$  under SBM

# A nonparametric view of network models and Newman–Girvan and other modularities

Peter J. Bickel<sup>a,1</sup> and Aiyou Chen<sup>b</sup>

## SPECTRAL CLUSTERING AND THE HIGH-DIMENSIONAL STOCHASTIC BLOCKMODEL

BY KARL ROHE, SOURAV CHATTERJEE AND BIN YU

*University of California Berkeley*

## Stochastic blockmodels with a growing number of classes

BY D. S. CHOI

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## THE METHOD OF MOMENTS AND DEGREE DISTRIBUTIONS FOR NETWORK MODELS

BY PETER J. BICKEL<sup>1</sup>, AIYOU CHEN<sup>2</sup> AND ELIZAVETA LEVINA<sup>3</sup>

*University of California, Berkeley, Google Inc. and University of Michigan*

## Consistency of maximum-likelihood and variational estimators in the Stochastic Block Model \*

Alain Celisse<sup>†</sup> et al

## A consistent adjacency spectral embedding for stochastic blockmodel graphs

Daniel L. Sussman, Minh Tang, Donniell E. Fishkind, Carey E. Priebe  
*Johns Hopkins University, Applied Math and Statistics Department*

## CONSISTENT BICLUSTERING

BY CHERYL J. FLYNN AND PATRICK O. PERRY

*New York University*

## ASYMPTOTIC NORMALITY OF MAXIMUM LIKELIHOOD AND ITS VARIATIONAL APPROXIMATION FOR STOCHASTIC BLOCKMODELS

BY PETER BICKEL, DAVID CHOI, XIANGYU CHANG, AND HAI ZHANG

*University of California, Berkeley*

*University of California, Berkeley*

*Xi'an Jiaotong University*

*Northwest University*

## CO-CLUSTERING FOR DIRECTED GRAPHS; THE STOCHASTIC CO-BLOCKMODEL AND A SPECTRAL ALGORITHM

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## Spectral Clustering of Graphs with General Degrees in the Extended Planted Partition Model

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## Classification and estimation in the Stochastic Block Model based on the empirical degrees

ANTOINE CHANNAROND

JEAN-JACQUES DAUDIN

AND STÉPHANE ROBIN

# Abstract

- What is the model? What are we estimating?
- **Previous parameterizations:**
  - Low-dimensional
  - Networks not transitive
- “Highest dimensional model”
  - Transitive
  - Easier estimation
  - Faster, local algorithms.

In previous work, the asymptotic settings have captured two features of empirical networks.

1) Sparse edges...

expected degree grows like  $\text{polylog}(n)$ .

would like to have constant expected degree

2) Fixed number of blocks or growing slowly.

best result:  $K = o(\sqrt{n})$ .

# Easier to consider the planted partition (aka four parameter SBM)

Recall that the Stochastic Blockmodel make clusters when  
Theta has large diagonal elements.  
and small off-diagonal elements.

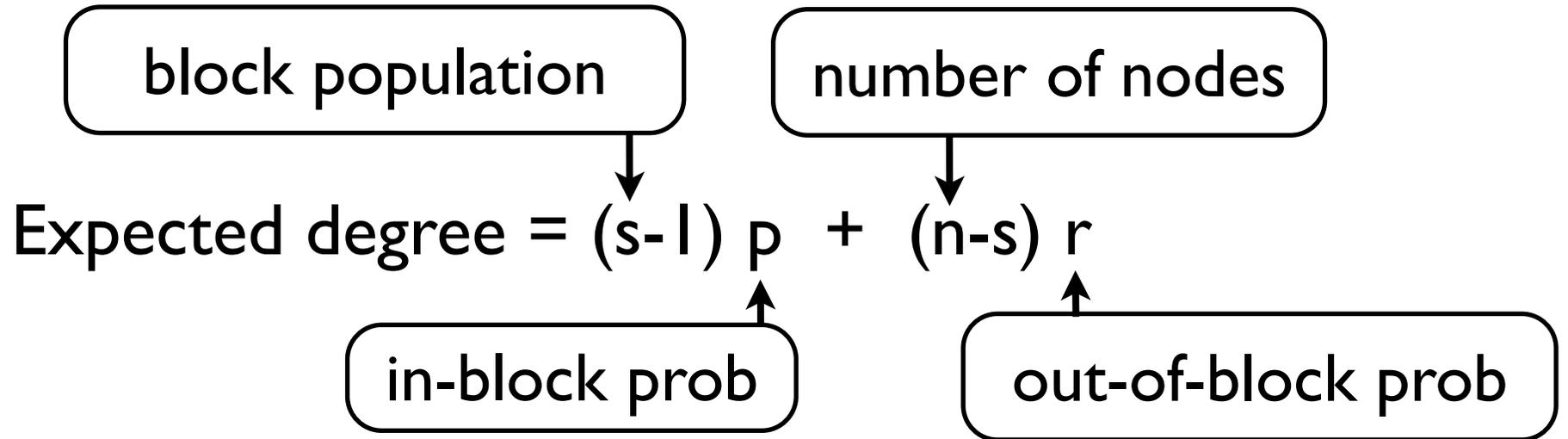
Four parameter model,  
constant diagonal  
constant off-diagonal  
equally sized blocks.

# Easier to consider the planted partition (aka four parameter SBM)

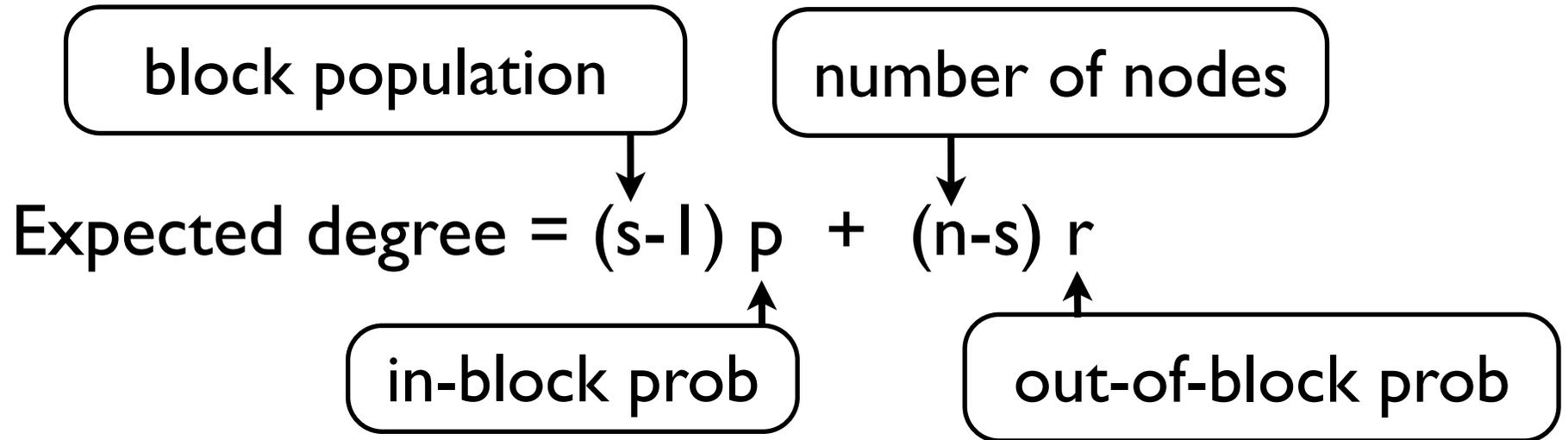
- $K$  = number of blocks
- $s$  = population of each block. Condition on  $Z$ .  
All blocks have equal population.
- $r$  = probability of an out-of-block connection
- $p$  = probability of an in-block connection

$$\text{So, } n = Ks$$

# Easy expression for expected degree.



# Easy expression for expected degree.



If the expected degree is polylog( $n$ ), then

$$p = O\left(\frac{\log^\alpha n}{s}\right) = O\left(\frac{K \log^\alpha n}{n}\right)$$

In previous work,  $p \rightarrow 0$ .

$$p = O\left(\frac{\log^\alpha n}{s}\right) = O\left(\frac{K \log^\alpha n}{n}\right)$$

Shrinking  $p$  has a dramatic effect  
on the clusters in the network

A similar assumption is made  
with more general models.

does not change with  $n$

$$P(A_{uv} = 1 | Z_u, Z_v) = \rho_n w(Z_u, Z_v)$$

“edge density” converges to zero

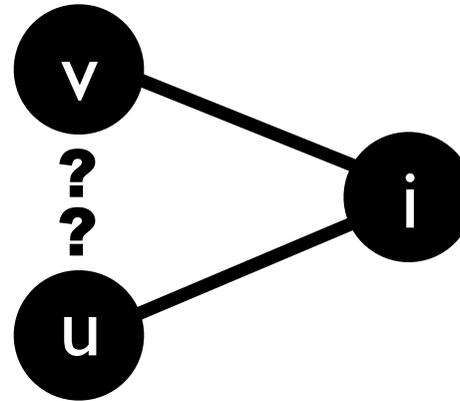
$$\rho_n = \frac{E(\text{number of edges})}{\binom{n}{2}}$$

In previous research,  
 $p_{\max}$  goes to zero.

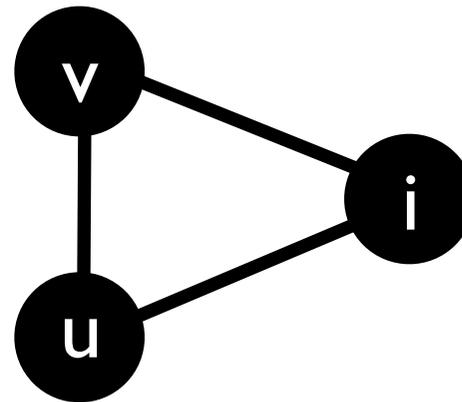
$$p_{\max} = \max_{Z_u, Z_v} P(A_{uv} = 1 | Z_u, Z_v)$$

This ensures sparsity.  
It also removes transitivity.

# Transitivity

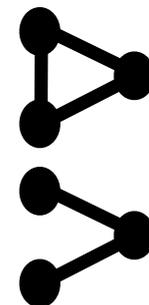


Friends of friends  
are friends



# Transitivity and the transitivity coefficient

$$\text{transitivity coefficient} = \frac{3 \times \text{number of triangles}}{\text{number of 2 stars}}$$



- “proportion of closed triangles”
- In social networks, this quantity is typically between .3 and .6 (Snijders slides).
- Extremely large networks also have non-negligible coefficients (Leskovec SNAP).

# Theorem

Under the exchangeable random graph model, if  $n\rho_n \rightarrow \infty$ ,  $\rho_n = o(1)$ , and  $p_{\max} = O(\rho_n)$  then,

$$\text{Transitivity Coefficient}(A) \xrightarrow{P} 0$$

recall: 
$$\rho_n = \frac{E(\text{number of edges})}{\binom{n}{2}}$$

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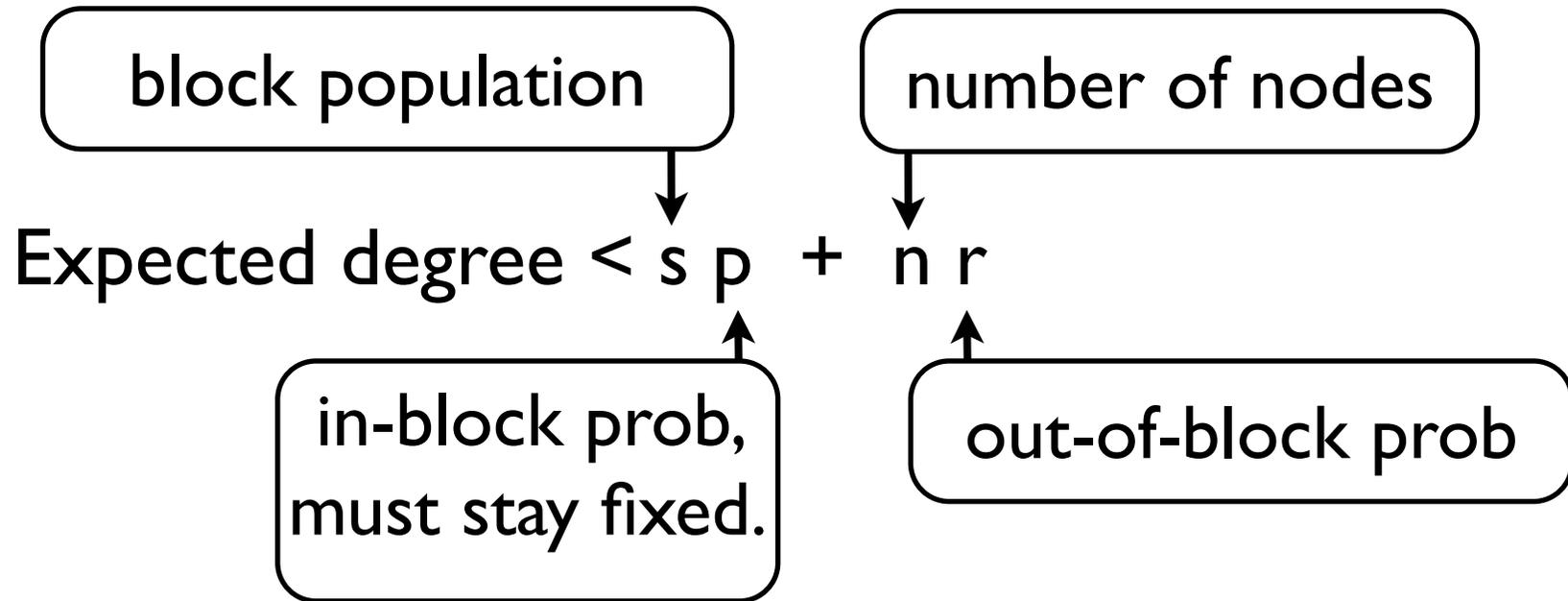
Conclusion: To preserve transitivity, it is necessary for  $p_{\max} > \epsilon > 0$ .

What parameters ensure a  
Stochastic Blockmodel with  
*sparsity and transitivity?*

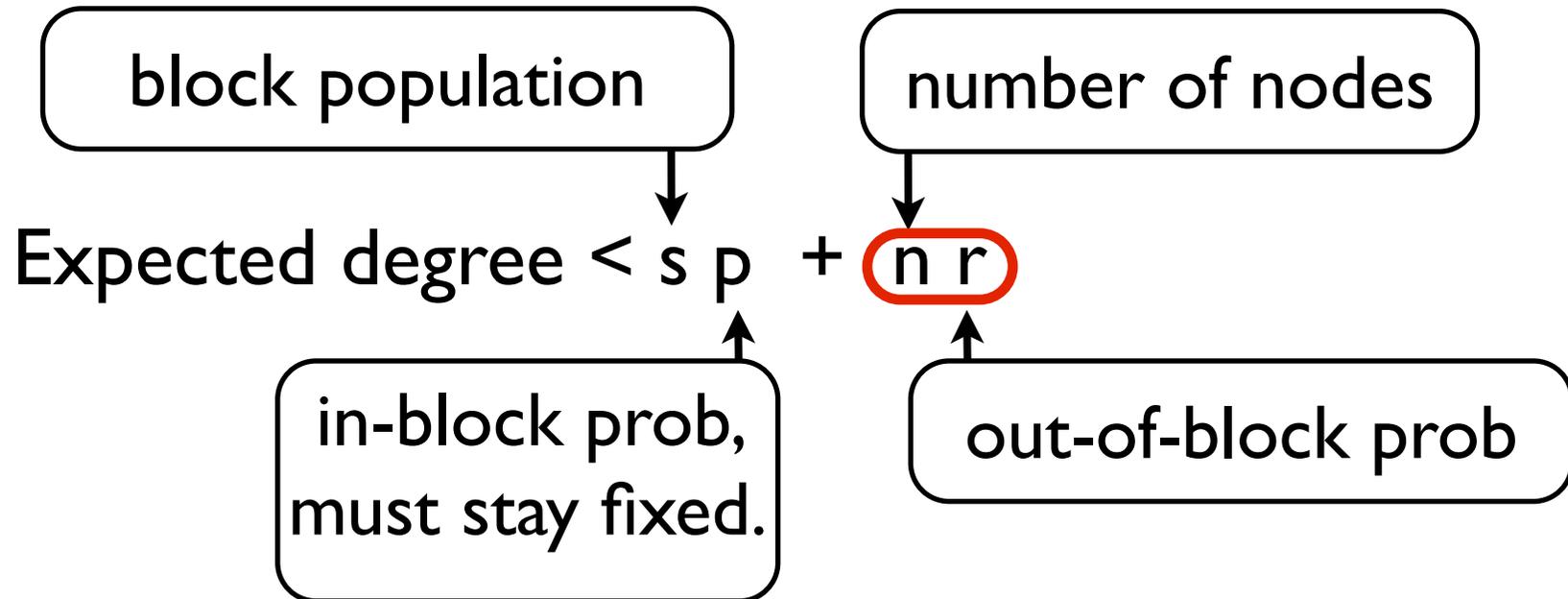
# Abstract

- What is the model? What are we estimating?
- Previous parameterizations:
  - Low-dimensional
  - Networks not transitive
- “Highest dimensional model”
  - Transitive
  - Better theoretical results
  - Faster, local algorithms.

# Want expected degree to be constant.

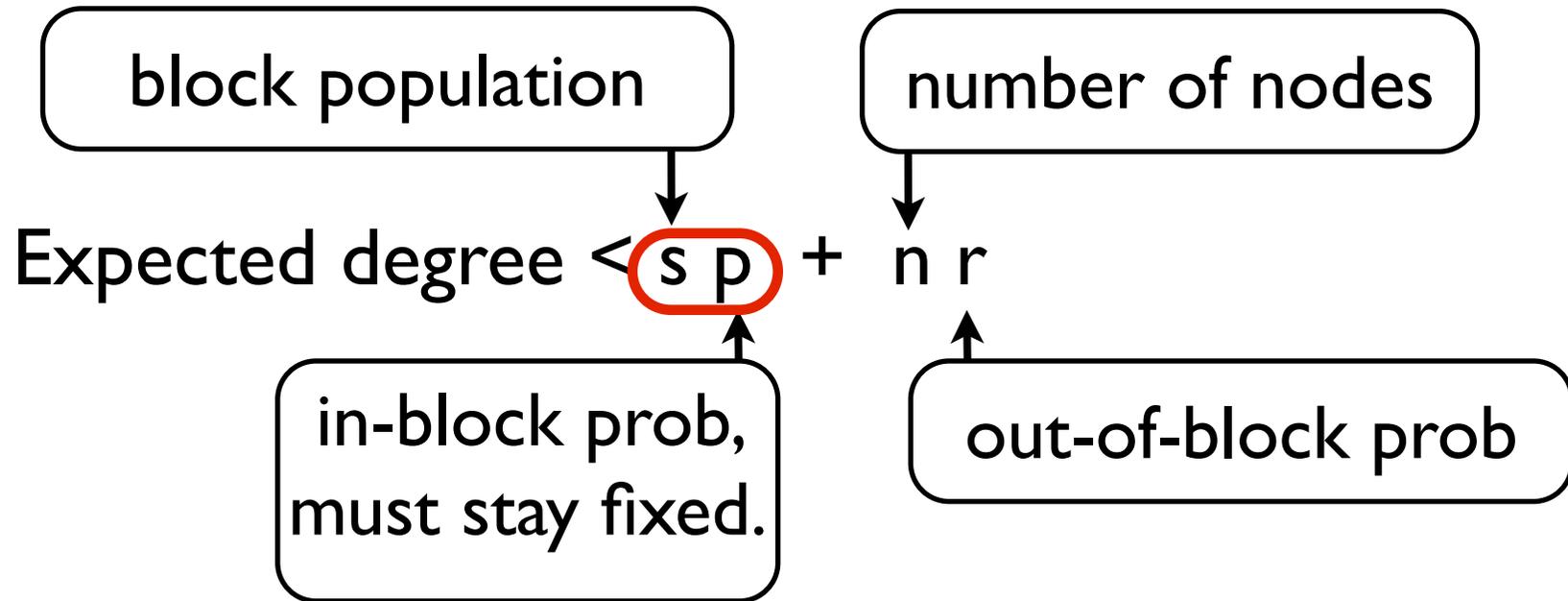


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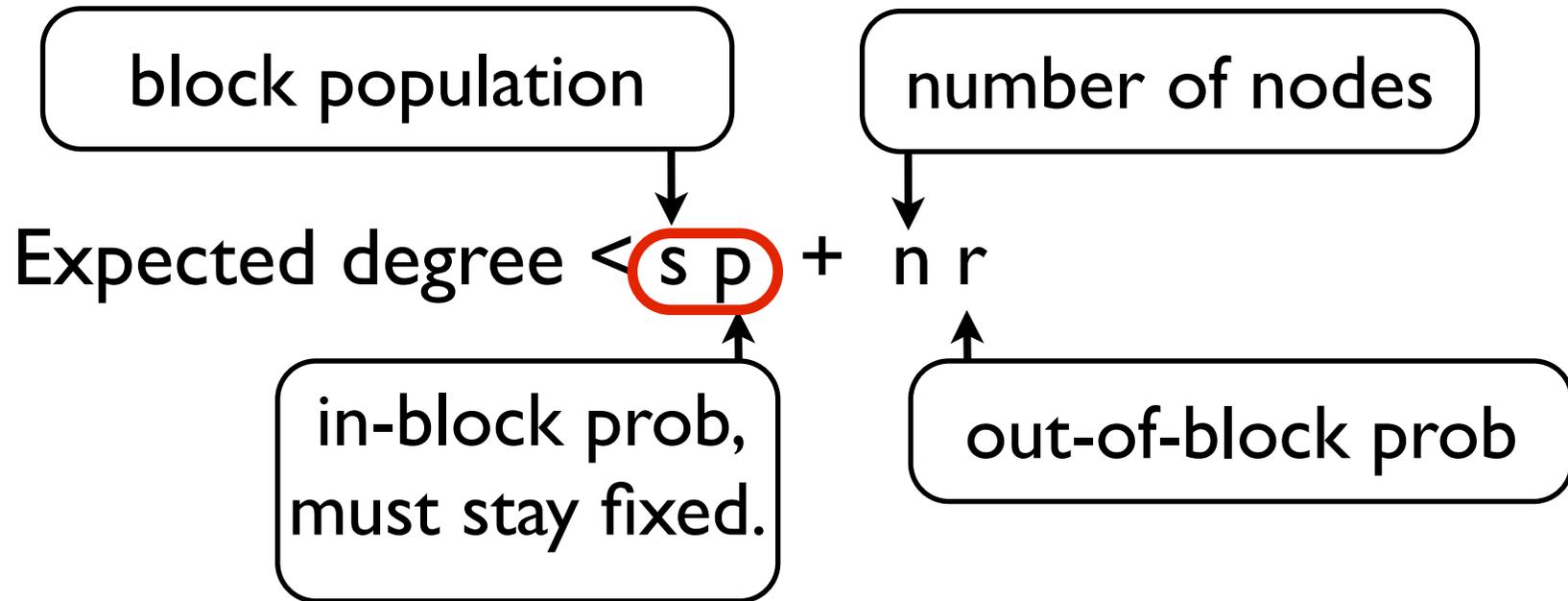
$$nr = C \text{ implies } r = O(1/n)$$

# Want expected degree to be constant.



$sp = C$  and  $p = p_{\max}$  not going to zero together imply that  $s$  (block population) does not grow.

# Want expected degree to be constant.



$sp = C$  and  $p = p_{\max}$  not going to zero together imply that  $s$  (block population) does not grow.

$n = Ks$  implies  $K$  must grow proportionally to  $n$ !

# Highest dimensional model yields transitivity & sparsity

- $K$  grows proportional to  $n$ .
- “Highest dimensional” because number of blocks cannot grow faster than number of nodes. Each block needs a member!
- Best results in the current literature require that  $K = o(\sqrt{n})$  (Choi et al 2012)

# Highest dimensional model is asymptotically transitive.

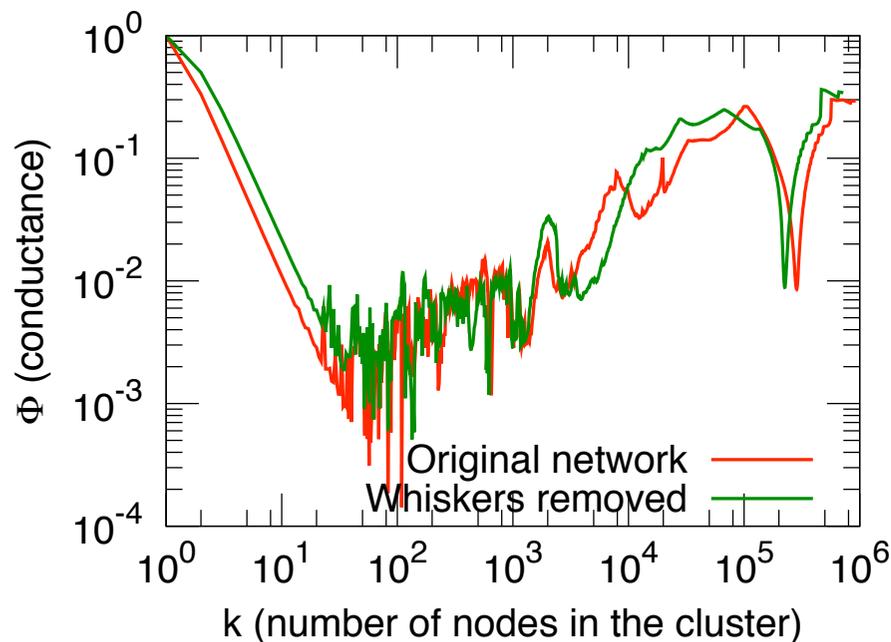
Proposition:

Under four-parameter SBM, with fixed  $s$ , fixed  $p > 0$ ,  
and  $r = c/n$ ,

$$\text{TransitivityCoefficient}(A) \xrightarrow{P} \frac{E(\text{number of triangles in } A|Z)}{E(\text{number of two stars in } A|Z)} > 0$$

# Empirical networks have small communities.

- Leskovec, Lang, Dasgupta, Mahoney 2008. In large empirical networks, “best clusters” are no larger than 100 nodes.



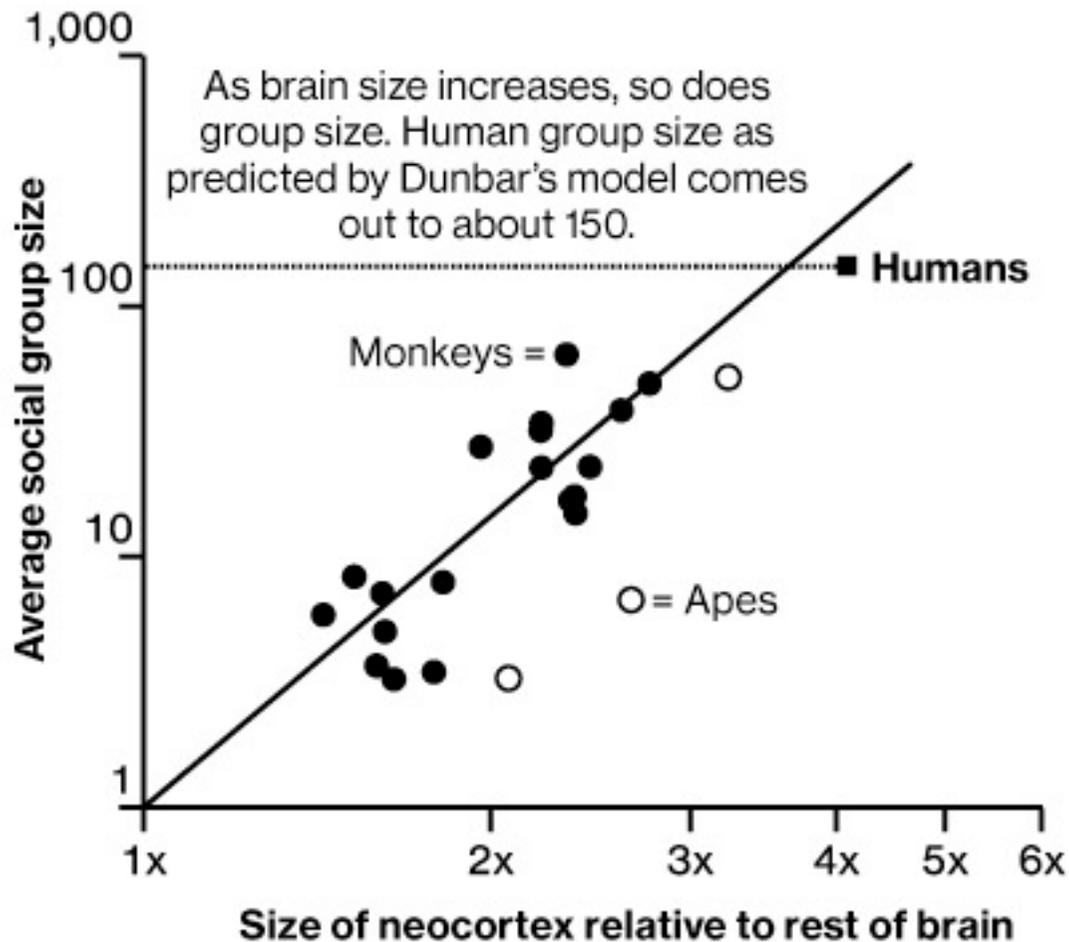
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# Biological evidence for small communities.

38 primates

# Biological evidence for small communities.

## The Social Cortex



# Abstract

- What is the model? What are we estimating?
- Previous parameterizations:
  - Low-dimensional
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- “Highest dimensional model”
  - Transitive
  - Easier estimation
  - Faster, local algorithms.

# Recall ...

The Stochastic Blockmodel sets

$$P(A_{uv} = 1 | Z_u, Z_v) = \Theta_{Z_u, Z_v}$$

for  $Z_i \in \{1, \dots, K\}$  and  $\Theta \in [0, 1]^{K \times K}$

# A regularized estimator

Log-likelihood:

$$L(A; z, \theta) = \sum_{i < j} \{A_{ij} \log \theta_{z_i z_j} + (1 - A_{ij}) \log(1 - \theta_{z_i z_j})\}.$$

standard MLE:  $\hat{z} = \arg \max_z \max_{\theta \in [0,1]^{K \times K}} L(A; z, \theta)$

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The restricted set,

$$R_K = \left\{ \theta \in [0, 1]^{K \times K} : \theta_{ab} = c, \forall a \neq b \text{ and for } c \in [0, 1] \right\}.$$

# Highest dimensional SBM

## 1) Small Blocks

The smallest block size  $b$  satisfies  $\frac{\log^4 n}{b} = o(1)$

## 2) Large in block prob, small out block prob

except for a small  
“exceptional set”  $Q$   
with large probabilities.



$$\Delta < \Theta_{ij} < 1 - \Delta$$
$$1/n^2 < \Theta_{ij} < C \log^3(n)/n$$

if  $i = j$  or  $(i, j) \in Q$   
otherwise

Delta and C are constants.

# Theorem

Under the Highest Dimensional SBM with

1) Not too many “exceptional” connections,

$$\left| \{(i, j) : (Z_i, Z_j) \in Q\} \right| = o(ns)$$

2) Sufficient separation between blocks,

For  $a \neq b$ , there exists  $c$  such that

$$D\left(\theta_{ac} \parallel \frac{\theta_{ac} + \theta_{bc}}{2}\right) + D\left(\theta_{bc} \parallel \frac{\theta_{ac} + \theta_{bc}}{2}\right) \geq C \frac{MK}{n^2}$$

where  $D(\parallel)$  is the KL divergence and  $M$  is the expected number of edges in the graph,

Under these conditions, the proportion of nodes misclustered by RMLE converges to zero:

$$\frac{N_e(\hat{z}^R)}{N} = o_p(1)$$

Proof extended from Choi et al 2012

# Definition of misclustered

A node is *correctly clustered* if its true class is in the majority within the estimated class.

$$N_e(\hat{z}^R)$$

The number of nodes whose true class is not the majority within its estimated class.

Off diagonal terms are all equal.

The restricted set,

$$R_K = \left\{ \theta \in [0, 1]^{K \times K} : \theta_{ab} = c, \forall a \neq b \text{ and for } c \in [0, 1] \right\}.$$

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$$R_K = \left\{ \theta \in [0, 1]^{K \times K} : \theta_{ab} = c, \forall a \neq b \text{ and for } c \in [0, 1] \right\}.$$

- All out-of-block probabilities estimated equal.
- Does not “fit to” between-block-edges.
  - doesn't move a node from block 9 to 10 based on it's connections to blocks 1, 2, 3, 4.
- Considers “in-block” connections, i.e. local connections, connections that reflect a high level of transitivity.

Note: Newman-Girvan modularity only measures local connections.

# Simulation

- Computing MLE or RMLE is difficult. Discrete optimization.
- **Key idea of RMLE: ignore the out of block edges.**  
**Act “locally” on the “high transitivity” edges.**

# Simulation

- This simulation compares
  - “Local” algorithm: agglomerative hierarchical clustering,
    - Dissimilarity measure inversely proportional to number of common neighbors, normalized by degree.
  - “Global” algorithm: spectral clustering
    - k-means on leading eigenvectors of the symmetric graph Laplacian.

# Simulation settings

- Each block has 15 members.
- The expected in-block degree is 8 (good edges).
- The expected out-of-block degree is 8 (bad edges).
- $K$ , number of blocks, grows from 20 to 195.

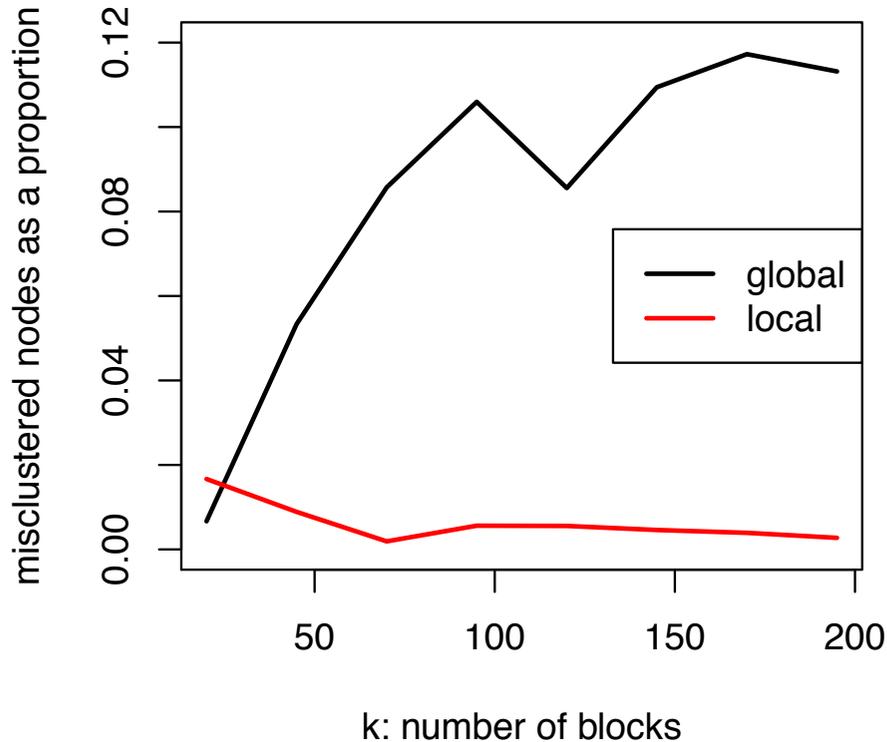
global = spectral clustering  
with symmetric graph  
Laplacian.

local = agglomerative  
hierarchical clustering with  
dissimilarity

$$d(i, j) = \frac{1}{[LL]_{ij} + .1}$$

↑  
symmetric graph Laplacian

Local outperforms global  
in highest dimensional scaling



LL contains “number of common neighbors,” normalized by degree.

# Recap

- For sparsity, current exchangeable models send  $p_{\max}$  to zero, removing transitivity.
- Empirical networks are transitive. Asymptotics should provide this.
- Transitivity leads to a blessing of dimensionality.
- Weak consistency with parametric regularization. Difficult to fit.
- Regularization through local methods, leveraging transitivity.

Define

$$p_{\max} = \max_{Z_u, Z_v} P(A_{uv} = 1 | Z_u, Z_v)$$

$$p_{\Delta} = P(A_{uv} = 1 | A_{iu} = A_{iv} = 1)$$

So,  $p_{\Delta} \leq p_{\max}$

When,  $h_n(u, v) = P(A_{uv} = 1 | Z_u, Z_v) = \rho_n w(u, v)$

$$p_{\Delta} \leq p_{\max} = O(\rho_n)$$

Sparse graph sends transitivity coefficient to zero.